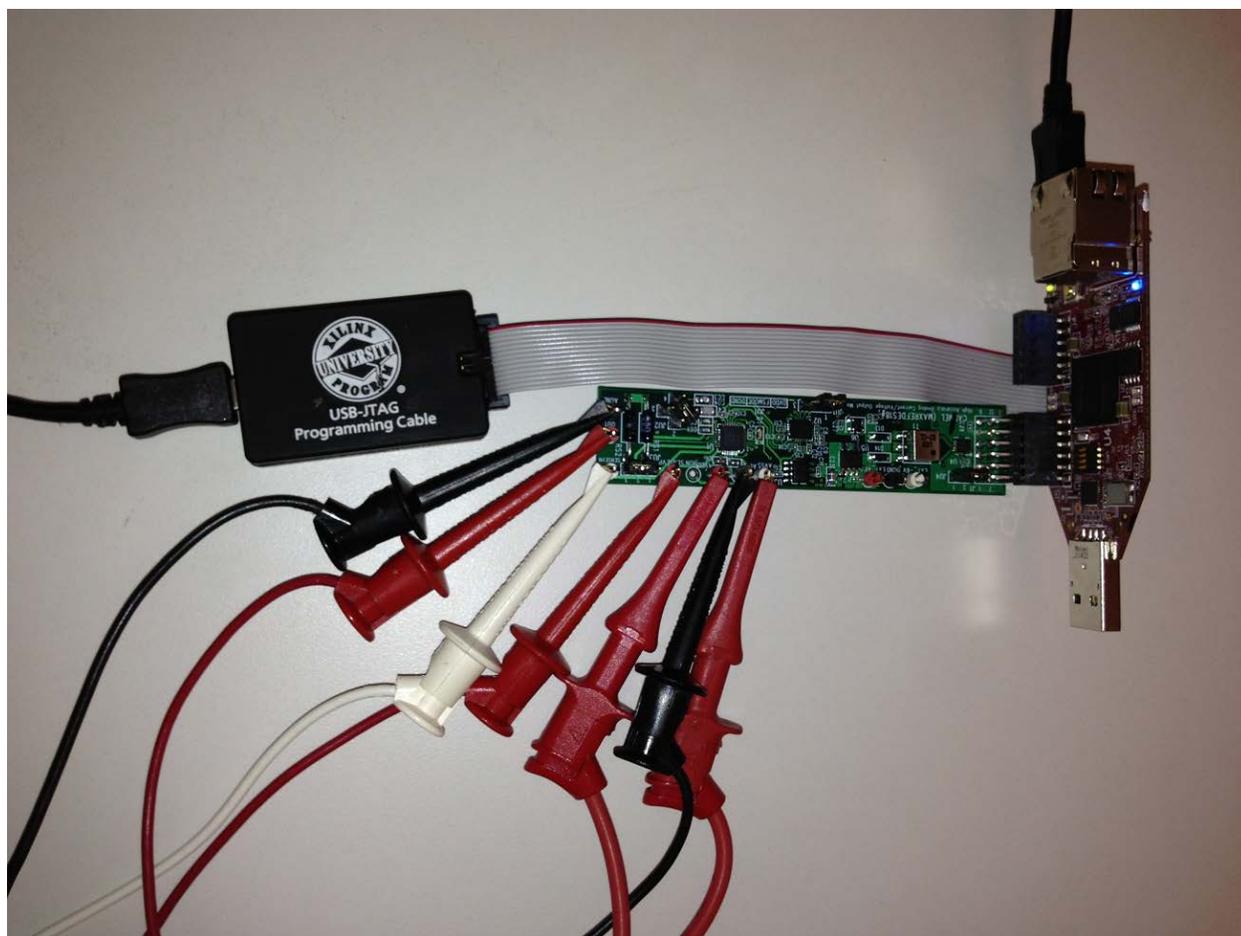




# Carmel (MAXREFDES18#) LX9 MicroBoard Quick Start Guide

Rev 0; 8/13



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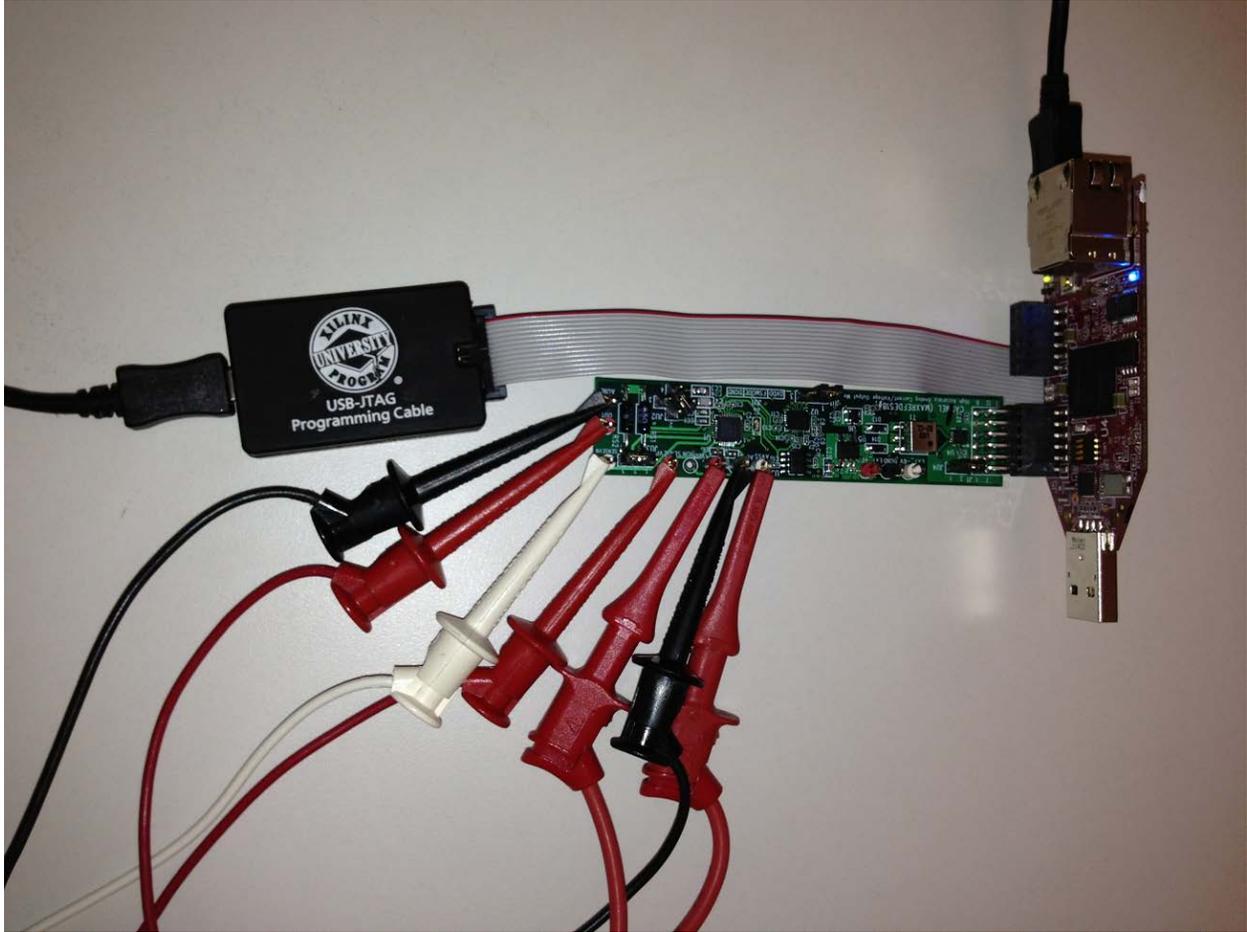
## 1. Required Equipment

- PC with Windows® OS with Xilinx® ISE®/SDK version 14.2 or later and two USB ports (Refer to Xilinx AR# 51895 if you installed ISE WebPack™ design software on your PC.)
- License for Xilinx EDK/SDK version 14.2 or later (free WebPack license is OK)
- Carmel (MAXREFDES18#) board
- Avnet Spartan®-6 LX9 MicroBoard
- One  $\pm 24V$  25mA minimum DC power supply
- One 750 $\Omega$  0.25W resistor

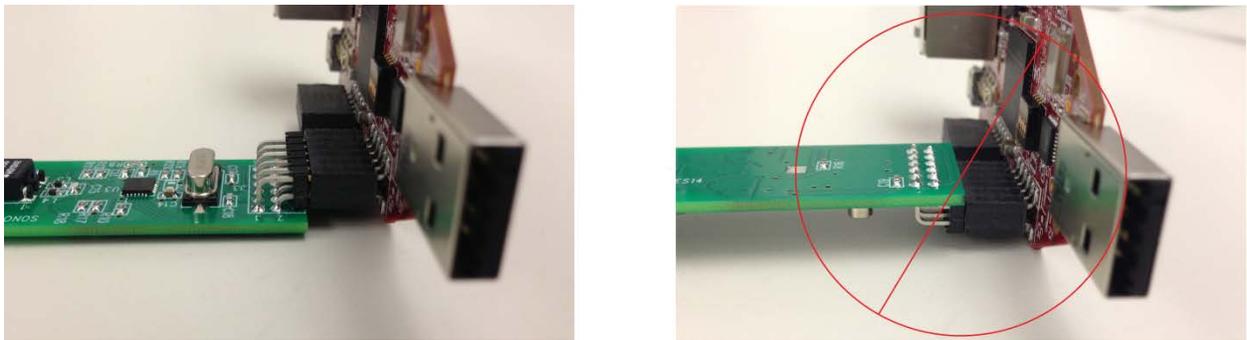
## 2. Overview

Below is a high-level overview of the steps required to quickly get the Carmel design running by downloading and running the FPGA project. Detailed instructions for each step are provided in the following pages. **The Carmel (MAXREFDES18#) subsystem reference design will be referred to as Carmel throughout this document.**

- 1) Connect the Carmel board to the J5 port of an LX9 MicroBoard as shown in [Figure 1](#). Ensure the connector is aligned as shown in [Figure 2](#).
- 2) Download the latest **RD18V01\_00.ZIP** file located at the Carmel page.
- 3) Extract the **RD18V01\_00.ZIP** file to a directory on your PC.
- 4) Open the Xilinx SDK.
- 5) Download the bitstream (.BIT) file to the board. This bitstream contains the FPGA hardware design and software bootloader.
- 6) Open a terminal program to communicate with FPGA board.
- 7) Use Xilinx SDK to download and run the executable file (.ELF) on the MicroBlaze™.



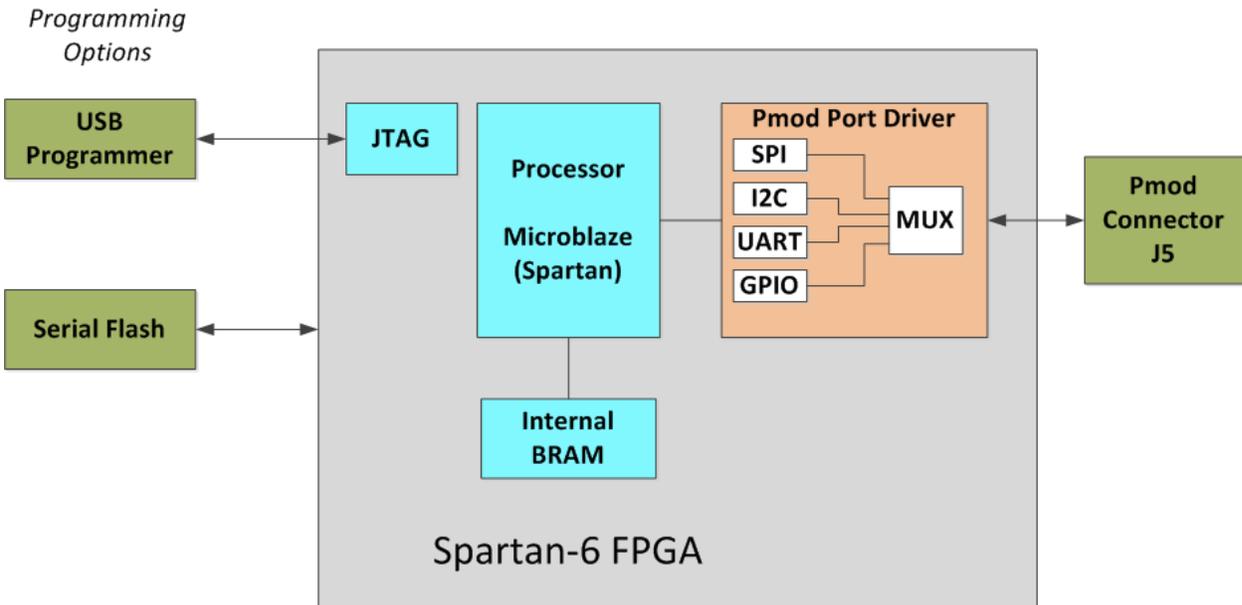
**Figure 1. Carmel Board Connected to LX9 Kit**



**Figure 2. Pmod™ Connector Alignment**

### 3. Included Files

The top level of the hardware design is a Xilinx ISE Project Navigator Project (.XISE) for Xilinx ISE version 14.2. The Verilog-based HDL design instantiates the MicroBlaze core, the support hardware required to run the MicroBlaze, and the peripherals that interface to the Pmod ports. Software is supplied as a Xilinx software development kit (SDK) project that includes a demonstration software application to evaluate the Carmel subsystem reference design. The lower level c-code driver routines are portable to the user's own software project.



\* SPI only used.

**Figure 3. Block Diagram of FPGA Hardware Design**

## 4. Procedure

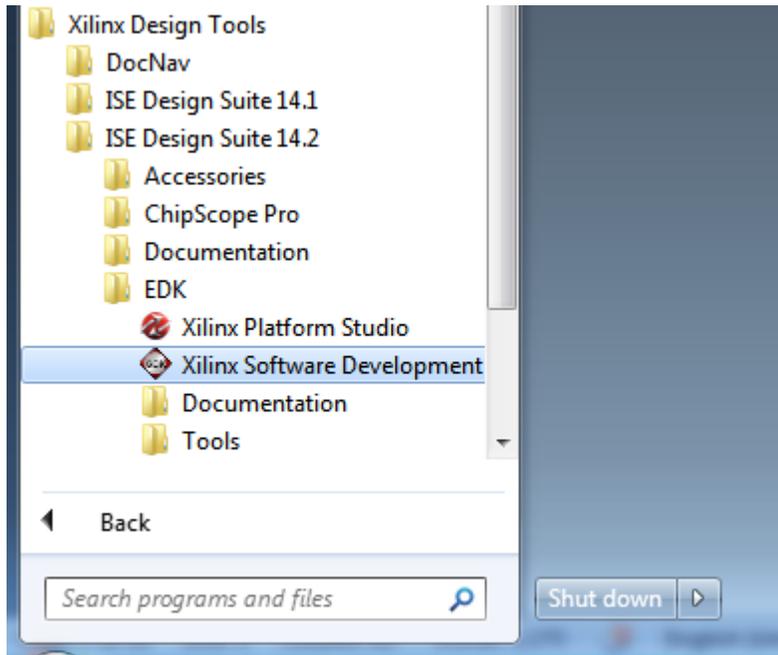
1. Connect the Carmel board to the J5 port of an LX9 MicroBoard as shown in [Figure 1](#).
2. Connect the  $\pm 24V$  power supply positive terminal, negative terminal, and the ground terminal to the AVDD, AVSS, and AGND connectors, respectively, on the Carmel board.
3. Connect one end of the  $750\Omega$  load resistor to the OUT and SENSEVP connectors on the Carmel board.
4. Connect the other end of the  $750\Omega$  load resistor to the AGND and SENSEVN connectors on the Carmel board.
5. Verify that the JU1 and JU4 jumpers are on the 1-2 position.
6. Verify that the JU2 jumper is on the pin 1 only.
7. Connect the J3 USB connector of the LX9 MicroBoard to a PC. Refer to step 16 for USB driver installation.
8. Connect the J6 JTAG connector of the LX9 MicroBoard to a PC through a Xilinx programming cable.
9. Download the latest **RD18V01\_00.ZIP** file at [www.maximintegrated.com/Carmel](http://www.maximintegrated.com/Carmel). All files available for download are available at the bottom of the page.
10. Extract the **RD18V01\_00.ZIP** file to a directory on your PC. The location is arbitrary but the maximum path length limitation in Windows (260 characters) should not be exceeded.

In addition, the Xilinx tools require the path to not contain any spaces.

**C:\Do Not Use Spaces In The Path\RD18V01\_00.ZIP**  
**(This path has spaces.)**

For the purposes of this document, it will be **C:\designs\maxim\RD18V01\_00\**. See [Appendix A: Project Structure and Key Filenames](#) in this document for the project structure and key filenames.

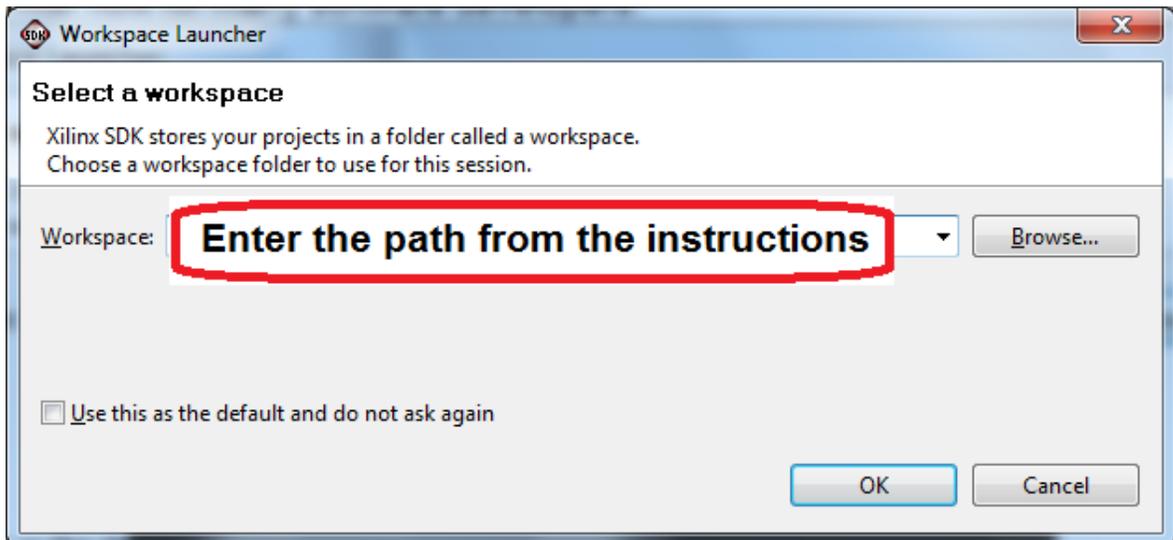
11. Open the **Xilinx Software Development Kit (SDK)** from the Windows **Start** menu.



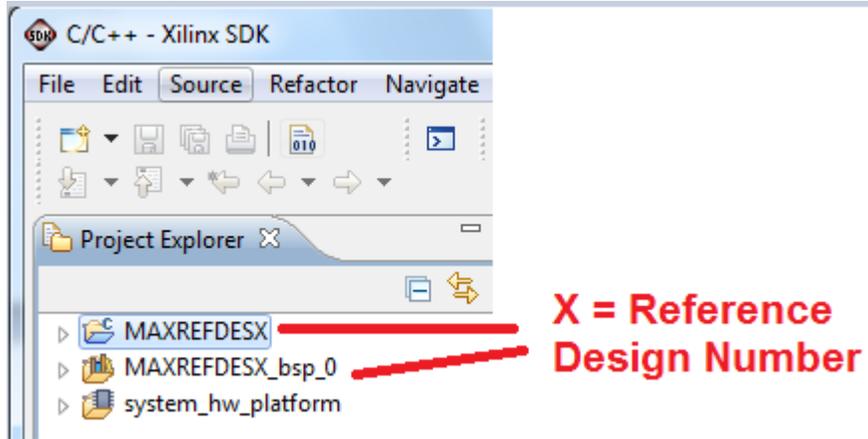
12. SDK will prompt for a workspace directory, which is the location where the software project is located. For this example, it is:

**C:\designs\maxim\RD18V01\_00\RD18\_LX9\_V01\_00\Design\_Files\sdkWorkspace**

Click **OK** and SDK will open. The Xilinx SDK is based on an Eclipse™-based IDE, so it will be a familiar flow for many software developers.



13. Review the SDK IDE. The **Project Explorer** in the upper left tab should have three components as shown in the image below. If all three subfolders are present, you can skip the next step.

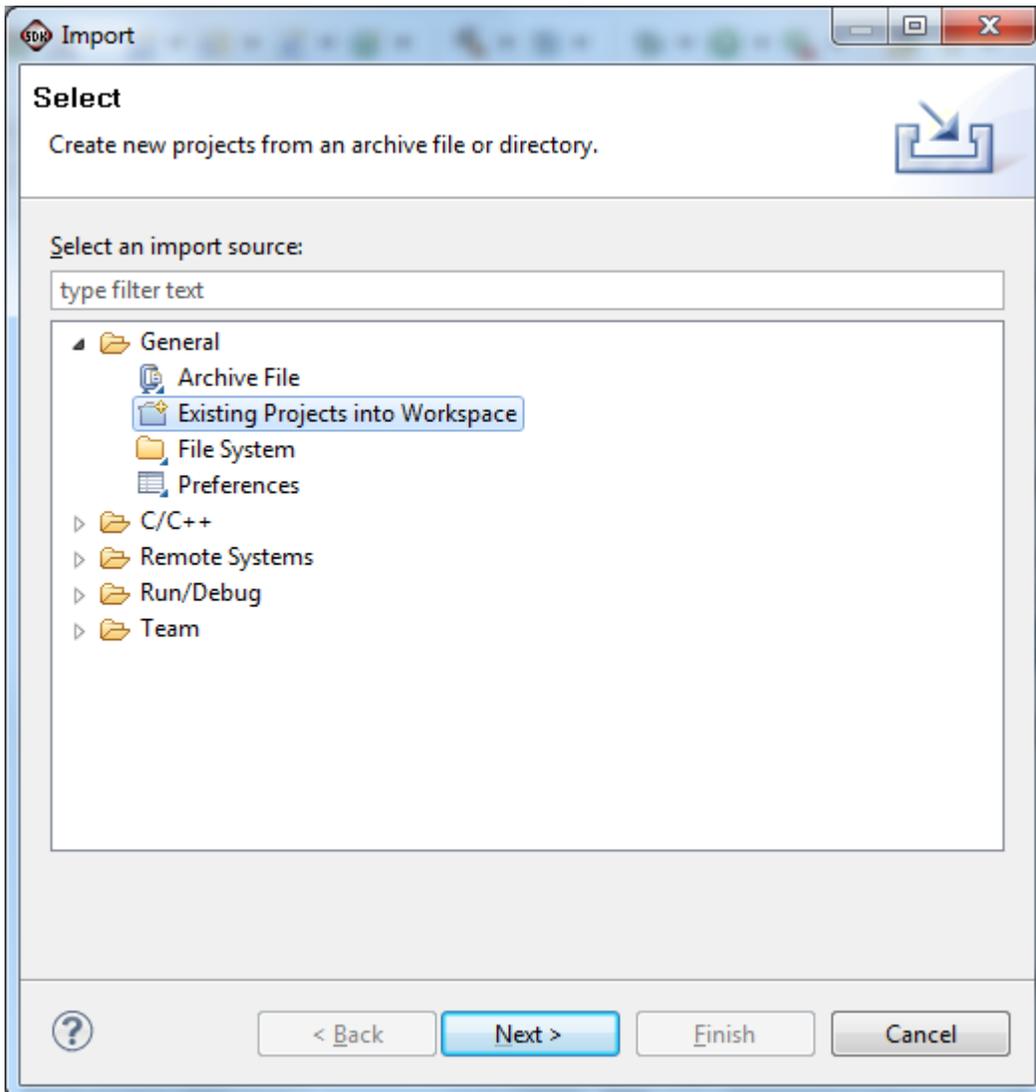


14. If the **Project Explorer** does not contain these three subfolders, launch the **File | Import** menu, expand the **General** folder, and select **Existing Projects into Workspace**. Click **Next**. Set the root directory to:

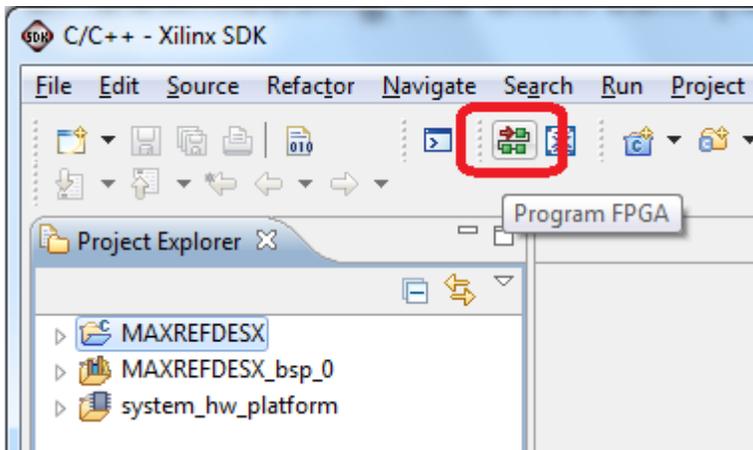
**C:\designs\maxim\RD18V01\_00\RD18\_LX9\_V01\_00\Design\_Files\sdkWorkspace**

and the missing projects should appear in SDK **Project Explorer** with their checkboxes checked.

Click **Finish** to import the projects.



15. To download the bitstream (.BIT) file to the board, click on the **Program FPGA** icon (which looks like a green chain of devices).



The Program FPGA dialog box appears. From here, an FPGA bitstream (.BIT) file is selected as well as an FPGA bmm (.BMM) file. Be sure to select the .BIT file and the .BMM by using the paths below.

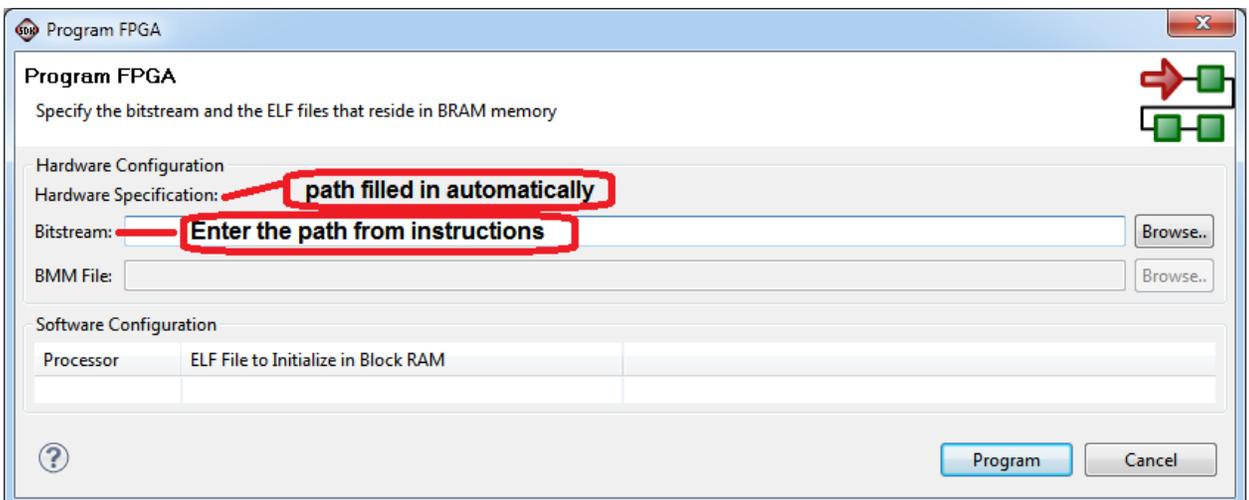
Bitstream:

**C:\designs\maxim\RD18V01\_00\RD18\_LX9\_V01\_00\Design\_Files\top.bit**

BMM File:

**C:\designs\maxim\RD18V01\_00\RD18\_LX9\_V01\_00\Design\_Files\edkBmmFile\_bd.bmm**

Also make sure the bootloop file is selected as shown, then press **Program**.



It takes approximately 10 seconds to download the FPGA, then a message box indicating **FPGA configuration complete** appears.

16. Setup of the terminal program to run on the PC using the following steps. Before loading the executable firmware file on the FPGA, the terminal program on the PC should be running. The example firmware running on the FPGA communicates with the PC via a USB port set up to emulate a serial port (UART). To establish this communication link, the PC must be configured with the appropriate Windows drivers. A suitable terminal program such as Tera Term or HyperTerminal should be invoked.

The micro USB (J3) on the LX9 is the communication port. The LX9 utilizes the Silicon Labs CP2102 USB-UART bridge IC, so you need to install Silicon Labs' virtual COM port (VCP) driver for their CP210x device family. These may be obtained from the Silicon Labs website ([www.silabs.com](http://www.silabs.com)).

Once installed, Windows will assign a previously unused COM port. Use the Windows **Control Panel | System | Device Manager** to determine the COM port number. (It will be named **Silicon Labs CP210x USB to UART Bridge**.) Make a note of which COM port this is. That information is needed in the next step.

Next, a terminal emulation program needs to be installed and launched. For Windows XP® and earlier systems, the HyperTerminal program is the usual choice. However, since HyperTerminal was eliminated from Windows 7, it may be necessary to locate an alternative. Several are available; one good choice is called Tera Term (<http://tssh2.sourceforge.jp/>). Whatever terminal program you choose, the communication should be set up by opening the COM port number previously described above and the port configured as:

bits per second: **115,200**;

data bits: **8**;

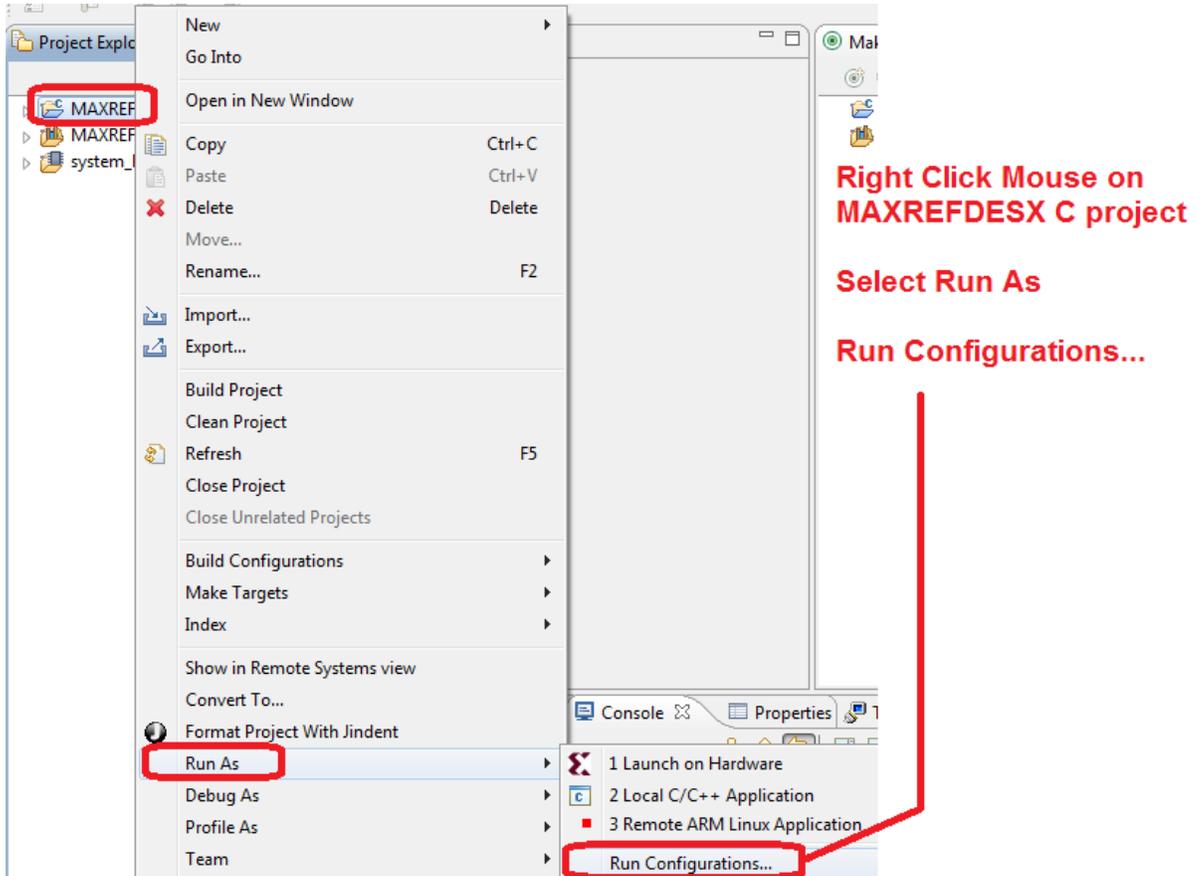
parity: **none**;

stop bits: **1**;

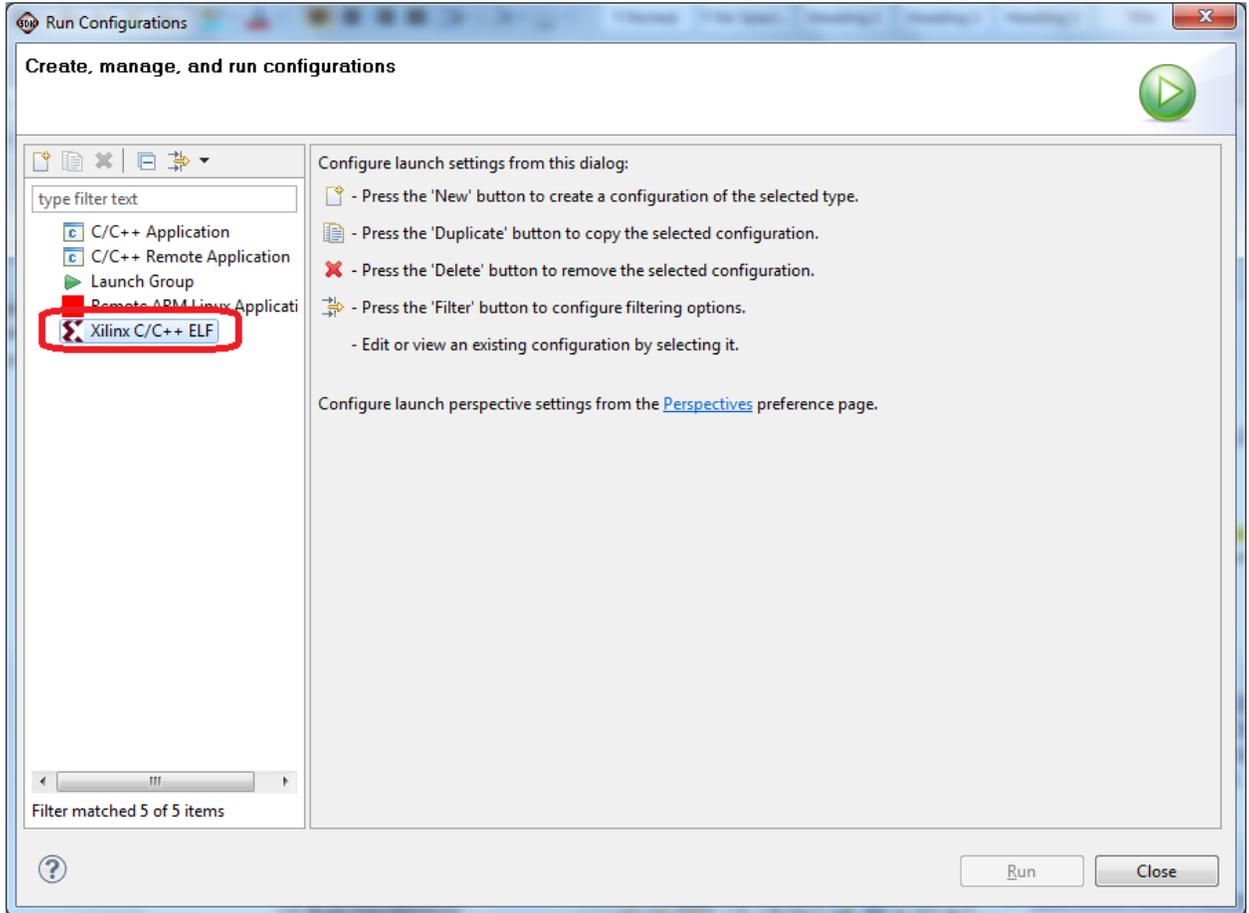
flow control: **none**.

17. Use the Xilinx SDK to download and run the executable ELF (.ELF) file on the MicroBlaze using the following steps.

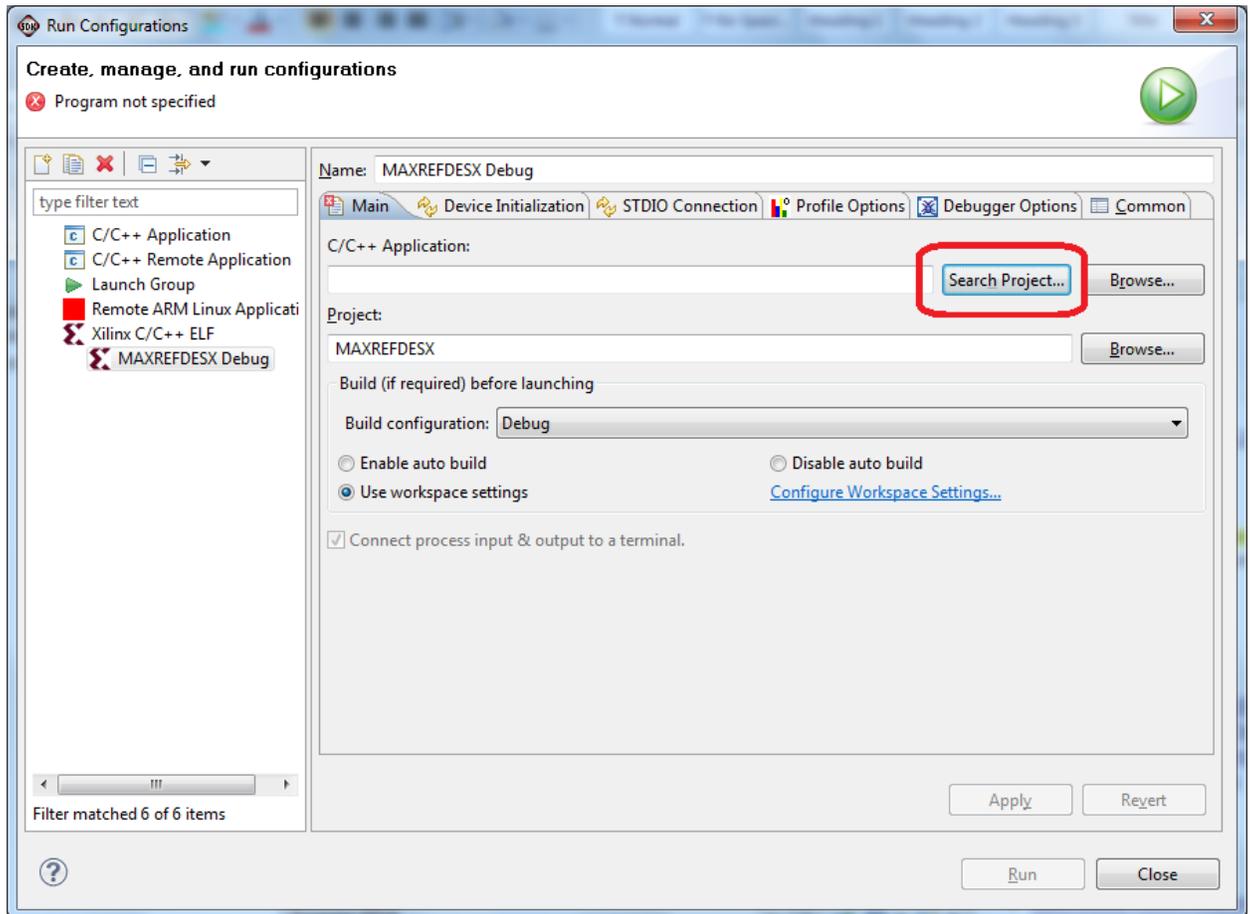
Right-click the mouse while the **MAXREFDES18 C** project is selected, choose the **Run As** menu, and then **Run Configurations...** menu as shown below.



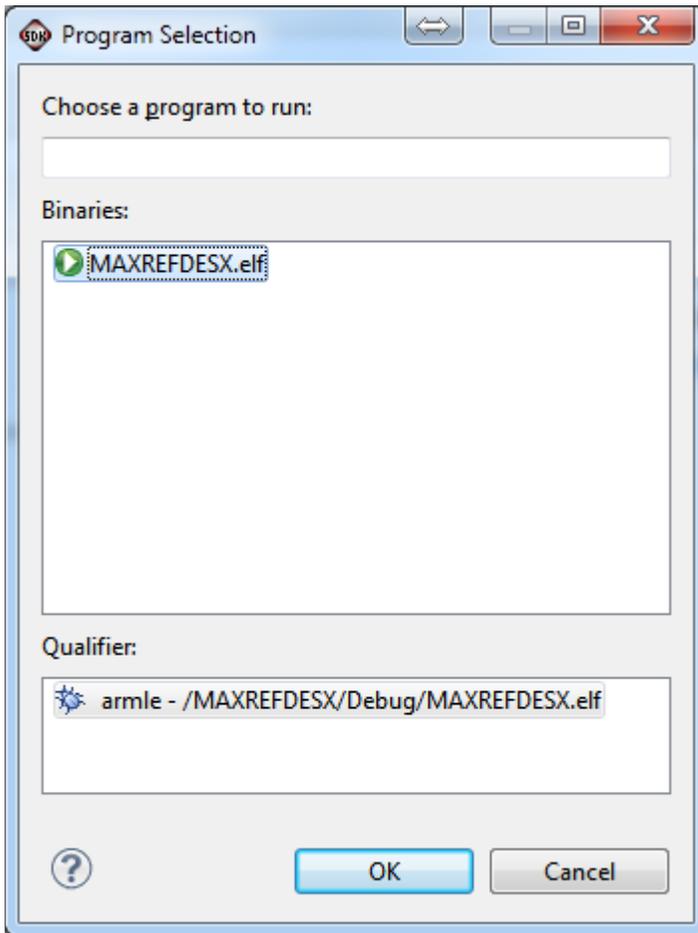
Next, double-click the mouse on the **Xilinx C/C++ ELF** menu.



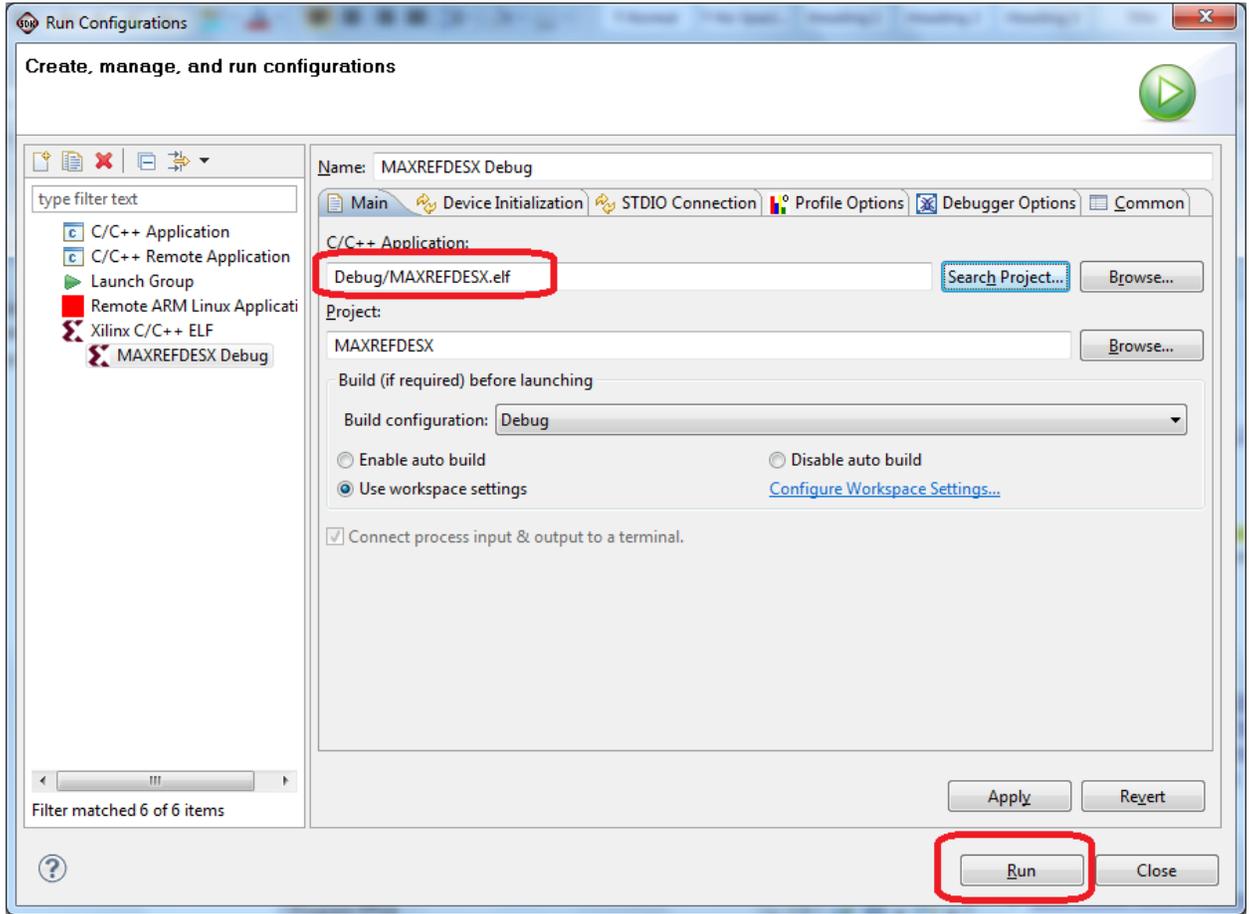
Next, press the **Search Project** button.



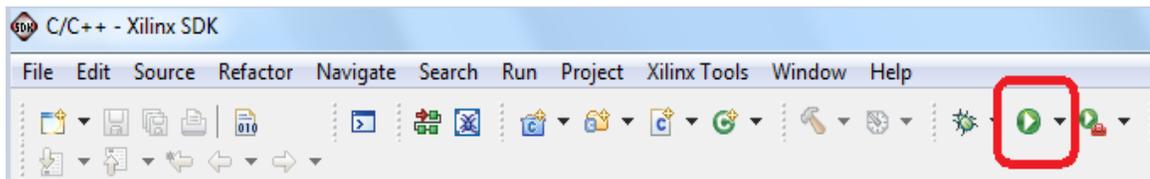
Double-click on the **MAXREFDES18.elf** binary.



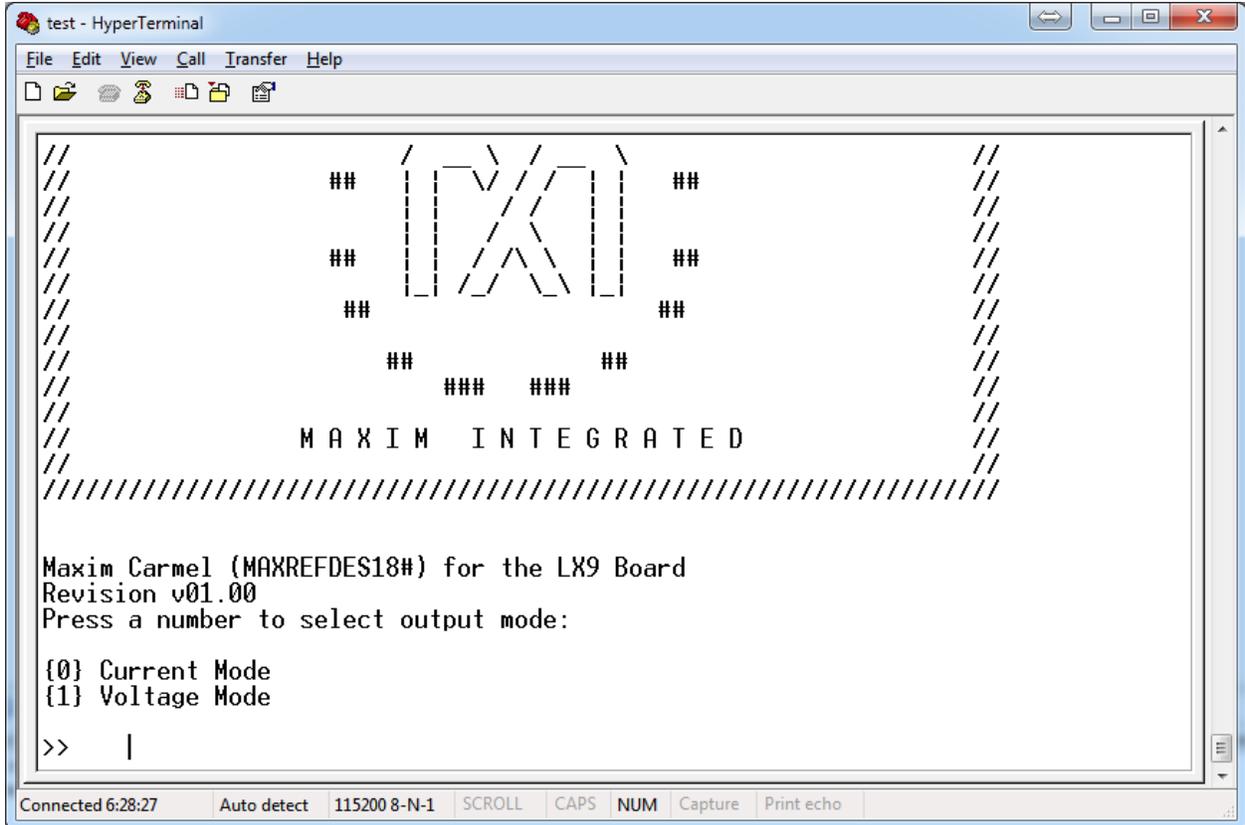
Verify the application is selected on the **Main** tab and press the **Run** button.



Once the Debug/MAXREFDES18 configuration is set up once, you just need to press the **Run** button if you ever want to run the program again.



At this point, the application will be running on the MicroBlaze and the terminal program should show the menu below. Make the desired selections by pressing the appropriate keys on the keyboard. For example, to select current output, press **0**.



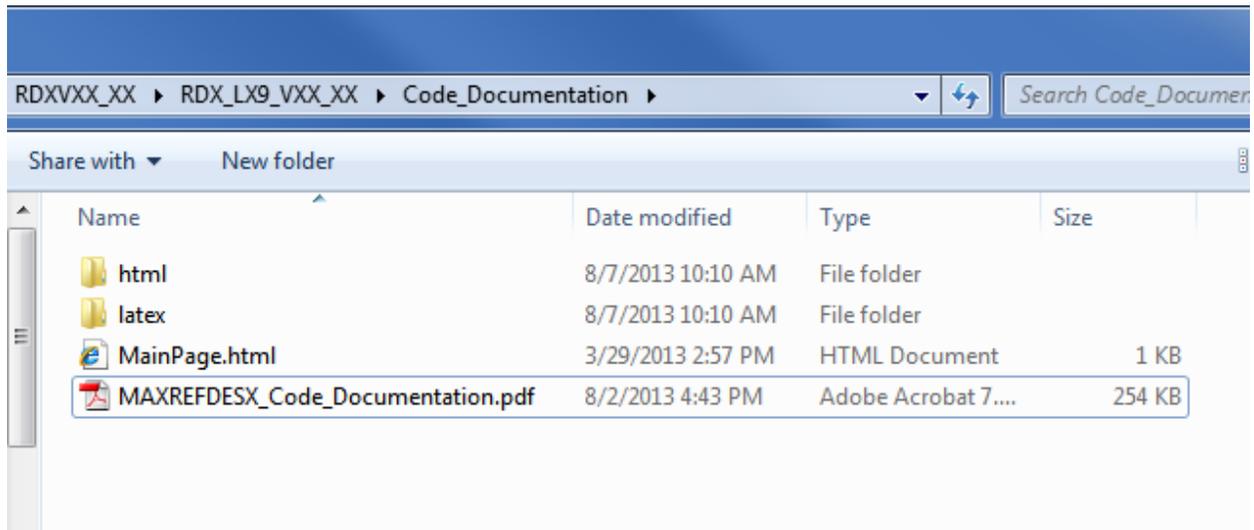
```
test - HyperTerminal
File Edit View Call Transfer Help
Maxim Carmel (MAXREFDES18#) for the LX9 Board
Revision v01.00
Press a number to select output mode:
{0} Current Mode
{1} Voltage Mode
>> |

////////////////////////////////////
```

## 5. Code Documentation

Code documentation can be found at:

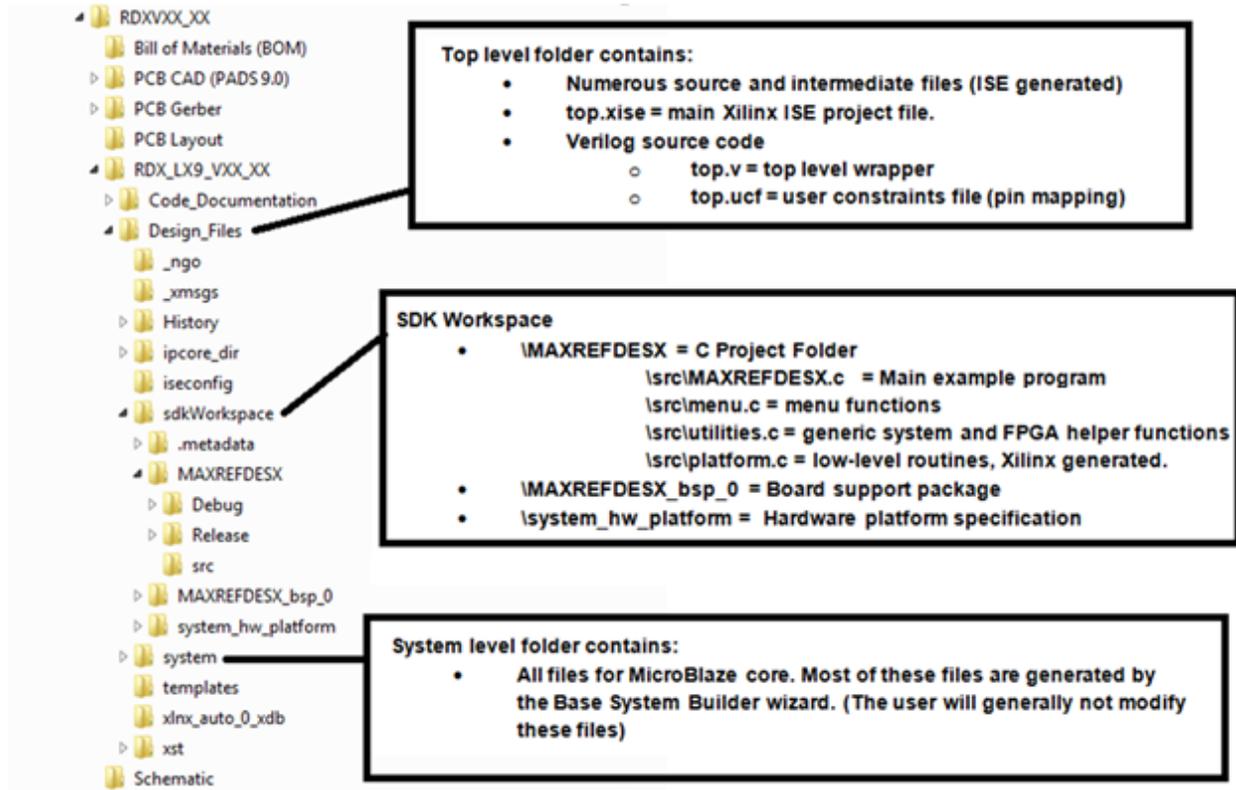
**C:\...\RD18V01\_00\RD18\_LX9\_V01\_00\Code\_Documentation\**



To view the code documentation in HTML format with a browser, open the **MainPage.html** file.

To view the code documentation in .PDF format with a PDF reader, open the **MAXREFDES18\_Code\_Documentation.pdf** file.

## 6. Appendix A: Project Structure and Key Filenames



## 7. Trademarks

Eclipse is a trademark of Eclipse Foundation, Inc.

MicroBlaze is a trademark of Xilinx, Inc.

Pmod is a trademark of Digilent Inc.

Spartan-6 is a registered trademark of Xilinx, Inc.

WebPACK is a trademark of Xilinx, Inc.

Windows is a registered trademark and registered service mark and Windows XP is a registered trademark of Microsoft Corporation.

Xilinx is a registered trademark and registered service mark of Xilinx, Inc.

## 8. Revision History

<b>REVISION NUMBER</b>	<b>REVISION DATE</b>	<b>DESCRIPTION</b>	<b>PAGES CHANGED</b>
0	8/13	Initial release	—