

# THCS251

35-bits GPIO or high speed Bus signal Transceiver

## General description

The THCS251 integrates Serializer and Deserializer onto a single chip, which supports general purpose input and output (GPIO) signals through two pairs of differential signal.

GPIO sampling clock is selectable from external reference clock or internal oscillator clock.

The 8B10B encoding and decoding adopted by THCS251 is easy to connect to optical / wireless communication devices with high robustness and DC balanced signal.

The built-in adaptive equalizer enables flexible cable selection.

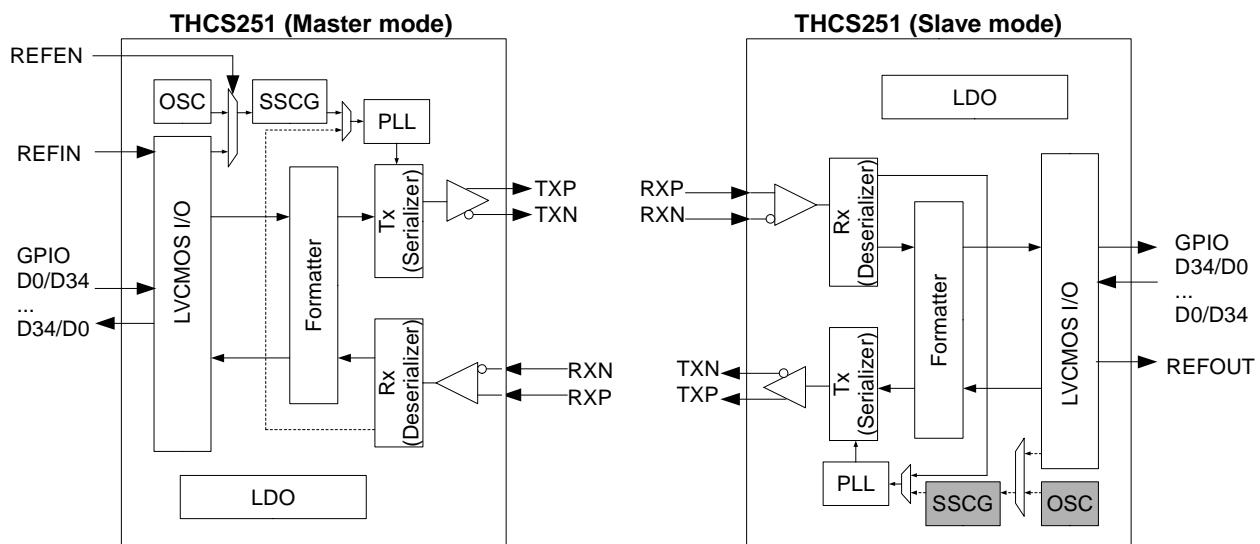
## Application

The THCS251 can applicable to any systems which have many control signals between PCBs, for example Multi-function printers, Amusement machines, Factory Automation and TVs.

## Features

- Support up to 35-bits GPIO
- Not required to input GPIO sampling clock in internal oscillator clock mode
- Full duplex communication by two pairs of differential signal
- Output buffer open-drain or push-pull selectable
- Support up to 8-bits low speed GPIO in low power Standby mode
- Integrated adaptive equalizer for long or lossy media
- 8B10B encoding and decoding
- Configurable digital noise filter
- Error detection and indication
- External reference clock frequency: 9-100MHz
- Spread Spectrum Clock Generator to reduce EMI
- Operating single power supply voltage: 1.7 V - 3.6 V
- Wide range IO voltage: 1.7V - 3.6V
- Operating temperature: -40°C to 85°C

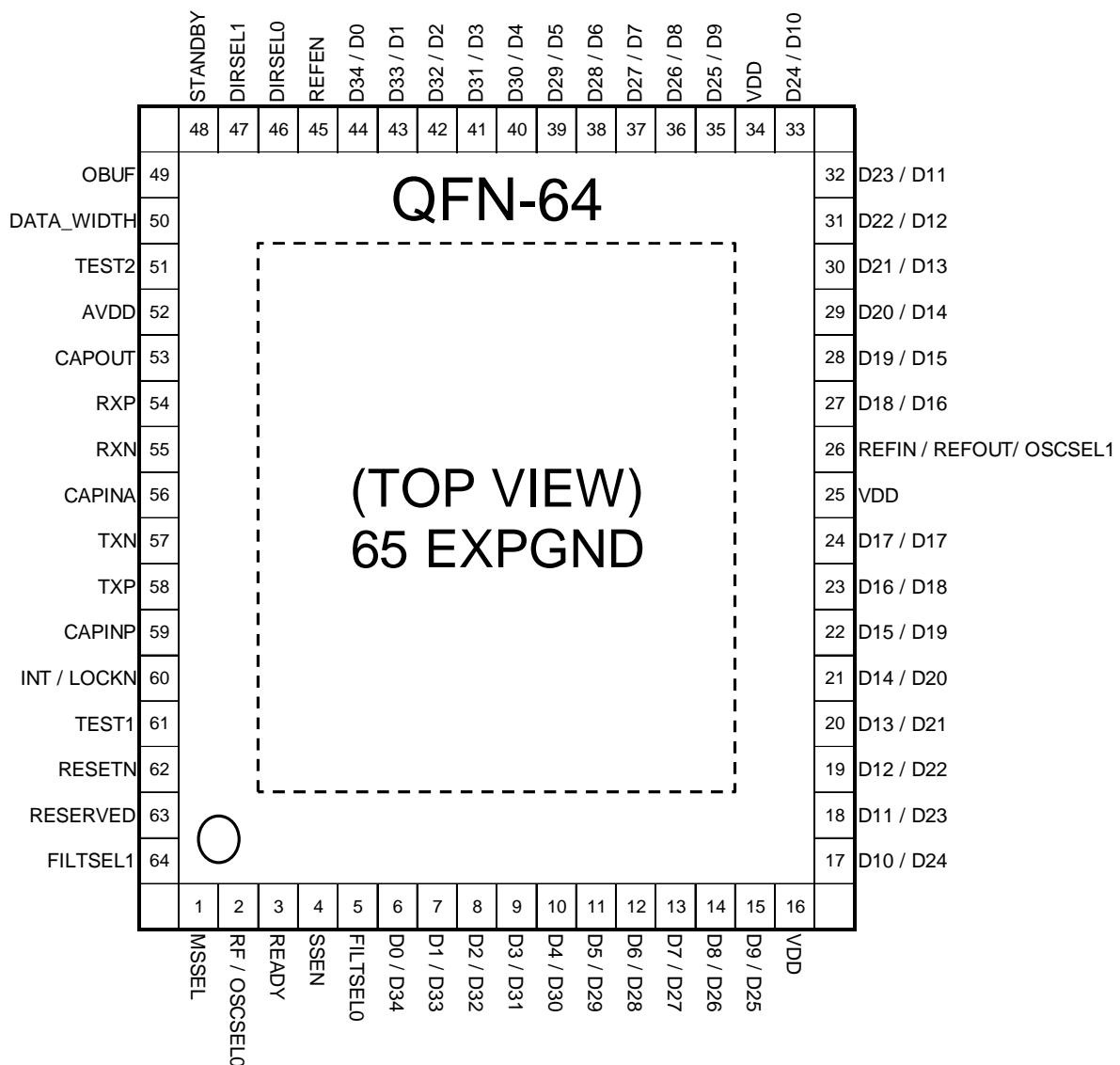
## Block diagram



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## 1. Pin configuration



## 2. Pin description

Pin Name	Pin No.	Type	Description	Reference
TXP	58	CO	High-speed CML signal output	-
TXN	57	CO	High-speed CML signal output	-
RXP	54	CI	High-speed CML signal input	-
RXN	55	CI	High-speed CML signal input	-
RESETN	62	IL	Chip reset 0: Chip reset 1: Chip operation	-
STANDBY	48	IL	Standby mode entry 0:Normal mode operation 1:Standby mode operation	-
RESERVED	63	IL	RESERVED shall be tied to Ground.	-
MSSEL	1	IL	Master/Slave mode select 0: Master mode 1: Slave mode	-
FILTSEL1	64	IL	FILTSEL1: digital noise filter select	Table 5
DIRSEL0	46	IL	DIRSEL0: GPIO direction select	Table 2 Table 4
DIRSEL1	47	IL	DIRSEL1: GPIO direction select	Table 2 Table 4
OBUF	49	IL	Output buffer type select 0: open-drain 1: push-pull	-
REFEN	45	IL	Data sampling clock select (Master mode) 0: Internal oscillator clock 1: External reference clock CDR clock output enable (Slave mode) 0: REFOUT pin is Hi-Z state 1: CDR clock output from REFOUT pin	- -
REFIN/ REFOUT/ OSCSEL1	26	B	REFIN: (Master mode) External Reference clock input REFOUT: (Slave mode) CDR clock output OSCSEL1: (Master mode) Oscillator clock frequency select OSCSEL1: (Slave mode) Hi-Z	- - Table 10 -
DATA_WIDTH	50	IL	GPIO Aggregator/Deaggregator data width select	Table 2 Table 4 Table 14
RF/ OSCSEL0	2	IL	RF:(Master mode) input clock edge select RF:(Slave mode) output clock edge select OSCSEL0: (Master mode) Oscillator clock frequency select	Table 11 Figure 14 Table 10

Pin Name	Pin No.	Type	Description	Reference
			OSCSEL0: (Slave mode) Set to Low	
D0/ D34	6	BT	D0(Master mode): Data input D34(Slave mode): Data output	-
D1/ D33	7	BT	D1(Master mode): Data input D33(Slave mode): Data output	-
D2/ D32	8	BT	D2(Master mode): Data input D32(Slave mode): Data output	-
D3/ D31	9	BT	D3(Master mode): Data input D31(Slave mode): Data output	-
D4/ D30	10	B	D4(Master mode): Data input D30(Slave mode): Data output	-
D5/ D29	11	B	D5(Master mode): Data input D29(Slave mode): Data output	-
D6/ D28	12	B	D6(Master mode): Data input D28(Slave mode): Data output	-
D7/ D27	13	B	D7(Master mode): Data input D27(Slave mode): Data output	-
D8/ D26	14	B	D8(Master mode): Data input D26(Slave mode): Data output	-
D9/ D25	15	B	D9(Master mode): Data input D25(Slave mode): Data output	-
D10/ D24	17	B	D10(Master mode): Data input D24(Slave mode): Data output	-
D11/ D23	18	B	D11(Master mode): Data input D23(Slave mode): Data output	-
D12/ D22	19	B	D12(Master mode): Data input D22(Slave mode): Data output	-
D13/ D21	20	B	D13(Master mode): Data input D21(Slave mode): Data output	-
D14/ D20	21	B	D14(Master mode): Data input/output D20(Slave mode): Data input/output	-
D15/ D19	22	B	D15(Master mode): Data input/output D19(Slave mode): Data input/output	-
D16/ D18	23	B	D16(Master mode): Data input/output D18(Slave mode): Data input/output	-
D17/ D17	24	B	D17(Master mode): Data input/output D17(Slave mode): Data input/output	-
D18/ D16	27	B	D18(Master mode): Data input/output D16(Slave mode): Data input/output	-
D19/ D15	28	B	D19(Master mode): Data input/output D15(Slave mode): Data input/output	-
D20/ D14	29	B	D20(Master mode): Data input/output D14(Slave mode): Data input/output	-
D21/ D13	30	B	D21(Master mode): Data input/output D13(Slave mode): Data input/output	-
D22/ D12	31	B	D22(Master mode): Data input/output D12(Slave mode): Data input/output	-

Pin Name	Pin No.	Type	Description	Reference
D23/ D11	32	B	D23(Master mode): Data input/output D11(Slave mode): Data input/output	-
D24/ D10	33	B	D24(Master mode): Data input/output D10(Slave mode): Data input/output	-
D25/ D9	35	B	D25(Master mode): Data input/output D9(Slave mode): Data input/output	-
D26/ D8	36	B	D26(Master mode): Data input/output D8(Slave mode): Data input/output	-
D27/ D7	37	B	D27(Master mode): Data input/output D7(Slave mode): Data input/output	-
D28/ D6	38	B	D28(Master mode): Data input/output D6(Slave mode): Data input/output	-
D29/ D5	39	B	D29(Master mode): Data input/output D5(Slave mode): Data input/output	-
D30/ D4	40	B	D30(Master mode): Data input/output D4(Slave mode): Data input/output	-
D31/ D3	41	BT	D31(Master mode): Data input/output D3(Slave mode): Data input/output	-
D32/ D2	42	BT	D32(Master mode): Data input/output D2(Slave mode): Data input/output	-
D33/ D1	43	BT	D33(Master mode): Data input/output D1(Slave mode): Data input/output	-
D34/ D0	44	BT	D34(Master mode): Data input/output D0(Slave mode): Data input/output	-
SSEN	4	BL	SSEN(Master mode): SSCG PLL enable 0: SSCG PLL is disabled 1: SSCG PLL is enabled  SSEN(Slave mode): Set to Low	-
FILTSEL0	5	BL	FILTSEL0: digital noise filter select	Table 5
INT/ LOCKN	60	BO	INT: Interrupt output when READY=1 0: Error occurred 1(pull-up): No Error	-
			LOCKN(Master mode): Lock detect input 0: Lock state 1(pull-up): Unlock state	-
			LOCKN(Slave mode): Lock detect output 0: Lock state 1(pull-up): Unlock state	-
READY	3	B	CML Link communication status 0: Unlock state 1: Lock state	-
TEST1	61	IL	TEST1 shall be tied to Ground.	-
TEST2	51	AI	TEST2 shall be tied to Ground.	-
CAPOUT	53	PWR	Decoupling capacitor Pin, 1.2V output.	Figure 9
CAPINA	56	PWR	1.2V Analog power supply input.	Figure 9

Pin Name	Pin No.	Type	Description	Reference
CAPINP	59	PWR	1.2V Analog power supply input.	Figure 9
VDD	16 25 34	PWR	1.7-3.6V Digital power supply input for LVCMOS I/O.	-
AVDD	52	PWR	1.7-3.6V Analog power supply input for on-chip regulator.	Figure 9
EXPGND	65	GND	Exposed Pad Ground. Must be tied to the PCB ground plane through an array of vias.	-

Pin Type definition

Analog Buffer

CO : CML Output buffer

CI : CML Input buffer

AI : Analog Input buffer

LVCMOS buffer

IL : Low speed schmitt trigger LVCMOS Input buffer

B : LVCMOS Bi-directional buffer

BO : Open-drain LVCMOS Bi-directional buffer

BL : Low speed 5V tolerant schmitt trigger LVCMOS Bi-directional buffer

BT : Low speed 5V tolerant LVCMOS Bi-directional buffer

Power/Ground

PWR : Power supply

GND : Ground

### 3. Absolute maximum ratings

Parameter	Min	Typ	Max	Unit
Supply voltage(VDD,AVDD)	-0.3	-	4.0	V
LVC MOS input voltage	-0.3	-	VDD+0.3	V
LVC MOS output voltage	-0.3	-	VDD+0.3	V
5V tolerant Bi-directional buffer input voltage	-0.3	-	VDD+2.5	V
5V tolerant Bi-directional buffer output voltage	-0.3	-	VDD+2.5	V
Open-drain output voltage	-0.3	-	4.0	V
CML receiver input voltage	-0.3	-	CAPINA+0.3	V
CML transmitter output voltage	-0.3	-	CAPINP+0.3	V
Output current	-50	-	50	mA
Storage temperature	-55	-	125	°C
Junction temperature	-	-	125	°C
Reflow peak temperature/time	-	-	260/10	°C/sec
Theta-ja (Junction-to-Ambient)	29.1 [*1]			°C/W
Psi-jt (Junction-to-Top of Package)	1.1 [*1]			°C/W
Maximum power dissipation @+25°C	3.4[*1]			W

“Absolute maximum ratings” are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits. The tables of “Electrical Characteristics” specify conditions for device operation.

\*1: Thermal parameters are not guaranteed value. This value assists board and system level designers.

### 4. Recommended operating conditions

Parameter	Min	Typ	Max	Unit
Supply voltage(VDD,AVDD)	1.7	-	3.6	V
Operating ambient temperature	-40	-	85	°C

VDD and AVDD supply voltage shall be the same voltage.

## 5. Electrical characteristics

### 5.1. Current consumption

Symbol	Parameter	Pin Type	Condition	Min	Typ	Max	Unit
Idd_w1	Normal mode current Low current use case [*1]	PWR	AVDD=3.3V VDD=3.3V	-	80	-	mA
Idd_w2	Normal mode current High current use case [*2]	PWR	AVDD=3.3V VDD=3.3V	-	260	-	mA
Idda_stby	Standby mode current	PWR	AVDD=3.3V VDD=3.3V	-	4	-	mA
Idda_slp	Sleep mode current	PWR	AVDD=3.3V VDD=3.3V	-	3	-	mA
Idda_RST	Reset mode current	PWR	AVDD=3.3V VDD=3.3V	-	3	-	mA

PWR : Power supply

\*1: Master mode of Unidirectional transmission mode, 35-bits GPIO input, 80MHz of REFIN clock

\*2: Slave mode of Unidirectional transmission mode, 35-bits GPIO output, 80MHz of REFOUT clock

**5.2. LVC MOS/Analog input DC specifications**

Symbol	Parameter	Pin Type	Condition	Min	Typ	Max	Unit
VIH	High level input voltage	B,BT, BO	1.7V≤VDD<2.0V	0.65 VDD	-	VDD	V
			2.0V≤VDD<3.0V	0.70 VDD	-	VDD	V
			3.0V≤VDD≤3.6V	2.0	-	VDD	V
		IL,BL	1.7V≤VDD≤3.6V	0.70 VDD	-	VDD	V
VIL	Low level input voltage	B,BT, BO	1.7V≤VDD<2.0V	0	-	0.35 VDD	V
			2.0V≤VDD<3.0V	0	-	0.30 VDD	V
			3.0V≤VDD≤3.6V	0	-	0.8	V
		IL,BL	1.7V≤VDD≤3.6V	0	-	0.30 VDD	V
		AI	1.7V≤VDD≤3.6V	0	-	0.15 VDD	V
VOH	High level output voltage	B,BT, BL	1.7V≤VDD<2.0V IOH=-2mA	VDD - 0.30	-	VDD	V
			2.0V≤VDD≤3.6V IOH=-4mA	VDD - 0.45	-	VDD	V
VOL	Low level output voltage	B,BT, BL	1.7V≤VDD<2.0V IOL=2mA	0	-	0.30	V
			2.0V≤VDD≤3.6V IOL=4mA	0	-	0.45	V
		BO	1.7V≤VDD≤3.6V IOL=2mA	0	-	0.27	V
IIH	Input leak current high	IL	VIN=VDD	-10	-	10	uA
IIL	Input leak current low	IL	VIN=0V	-10	-	10	uA
IOZH	Output leak current high in Hi-Z state	B,BT, BL,BO	VIN=VDD	-10	-	10	uA
IOZL	Output leak current low in Hi-Z state	B,BT, BL,BO	VIN=0V	-10	-	10	uA

AI : Analog Input buffer

IL : Low speed schmitt trigger LVC MOS Input buffer

B : LVC MOS Bi-directional buffer

BO : Open-drain LVC MOS Bi-directional buffer

BL : Low speed 5V tolerant schmitt trigger LVC MOS Bi-directional buffer

BT : Low speed 5V tolerant LVC MOS Bi-directional buffer

**5.3. LVCMOS AC characteristics**

Symbol	Parameter	Condition	Min	Typ	Max	Unit	
tRSN	RESETN low time	-	3	-	-	us	
tTCIP	REFIN period	DATA_WIDTH=0	10	-	66.6	ns	
		DATA_WIDTH=1	12.5	-	111	ns	
tTCH	REFIN high time	-	0.35 tTCIP	0.5 tTCIP	0.65 tTCIP	ns	
tTCL	REFIN low time	-	0.35 tTCIP	0.5 tTCIP	0.65 tTCIP	ns	
tTS	Data input setup to REFIN	Pin type: B  Pin type: BT	1.7V≤VDD≤3.6V  1.7V≤VDD<2.25V 2.25V≤VDD≤2.75V 2.75V<VDD≤3.6V	2.0  25 2.5 2.0	-  - - -	-  ns ns ns	
		-	1.0	-	-	ns	
tTPD	Power on to RESETN high delay	-	0	-	-	ns	
tOSC	Internal oscillator clock period	OSCSEL1=0 OSCSEL0=0	41.67	50	62.5	ns	
		OSCSEL1=1 OSCSEL0=0	20.84	25	31.25	ns	
		OSCSEL1=1 OSCSEL0=1	10.42	12.5	15.62	ns	
tDCP	Data sampling clock period	REFEN=0	-	tOSC	-	ns	
		REFEN=1	-	tTCIP	-	ns	
tFLTCK	Noise filter clock period	REFEN=0	10.42	12.5	15.62	ns	
		REFEN=1	-	tTCIP	-	ns	
tTCD	Input data to output data delay (Master mode to Slave mode)	SSEN=0	FILTSEL1=0 FILTSEL0=0	12 tDCP	-	25 tDCP	ns
			FILTSEL1=0 FILTSEL0=1	19 tDCP	-	35 tDCP	ns
			FILTSEL1=1 FILTSEL0=0	24 tDCP	-	43 tDCP	ns
			FILTSEL1=1 FILTSEL0=1	34 tDCP	-	59 tDCP	ns
			FILTSEL1=0 FILTSEL0=0	57 tDCP	-	110 tDCP	ns
		SSEN=1	FILTSEL1=0 FILTSEL0=1	64 tDCP	-	120 tDCP	ns
			FILTSEL1=1 FILTSEL0=0	69 tDCP	-	128 tDCP	ns
			FILTSEL1=1 FILTSEL0=1	79 tDCP	-	144 tDCP	ns
tRCP	REFOUT period	-	-	tDCP	-	ns	
tRCH	REFOUT high time	-	-	0.5 tDCP	-	ns	
tRCL	REFOUT low time	-	-	0.5 tDCP	-	ns	
tDOUT	Data output period	-	-	tDCP	-	ns	
tRS	Data output setup to REFOUT	-	0.45 tDCP - 0.675	-	-	ns	
tRH	Data output hold to REFOUT	-	0.45 tDCP - 2.175	-	-	ns	
tRCD	Input data to output data delay (Slave mode to Master mode)	FILTSEL1=0 FILTSEL0=0	12 tDCP	-	25 tDCP	ns	
		FILTSEL1=0 FILTSEL0=1	19 tDCP	-	35 tDCP	ns	
		FILTSEL1=1 FILTSEL0=0	24 tDCP	-	43 tDCP	ns	
		FILTSEL1=1	34 tDCP	-	59 tDCP	ns	

Symbol	Parameter	Condition	Min	Typ	Max	Unit
		FILTSEL0=1				
tRRDY	RESETN high to READY high delay	-	0	-	10	ms
tNRDY	STANDBY low to READY high delay	-	0	-	10	ms
tSRDY	STANDBY high to READY high delay	-	0	-	10	ms
tSSKW	STANDBY high of Master mode and Slave mode skew margin	-	-400	-	+400	us
tTLH	Clock and Data output low to high transition time	Clock	-	-	2.1	ns
		Data(Pin type=B)	-	-	4.2	ns
		Data(Pin type=BT)	-	-	5.9	ns
tTHL	Clock and data output high to low transition time	Clock	-	-	2.1	ns
		Data(Pin type=B)	-	-	4.3	ns
		Data(Pin type=BT)	-	-	6.1	ns

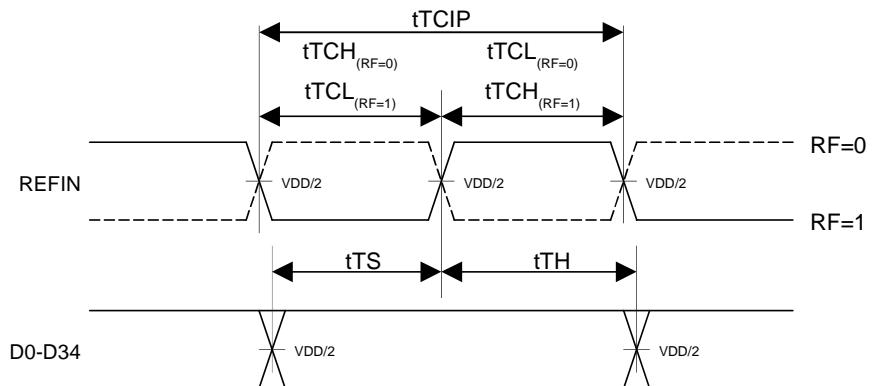
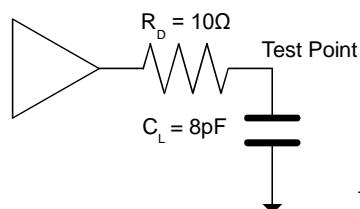


Figure 1 LVC MOS input timing diagram



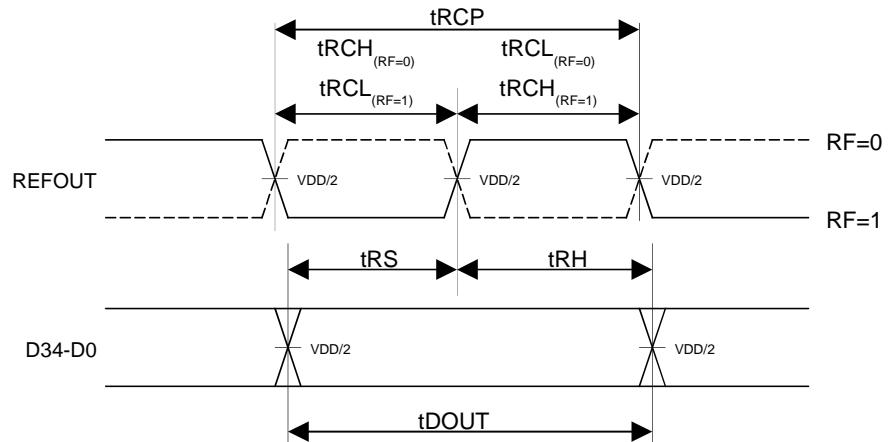


Figure 2 LVCMOS output timing diagram

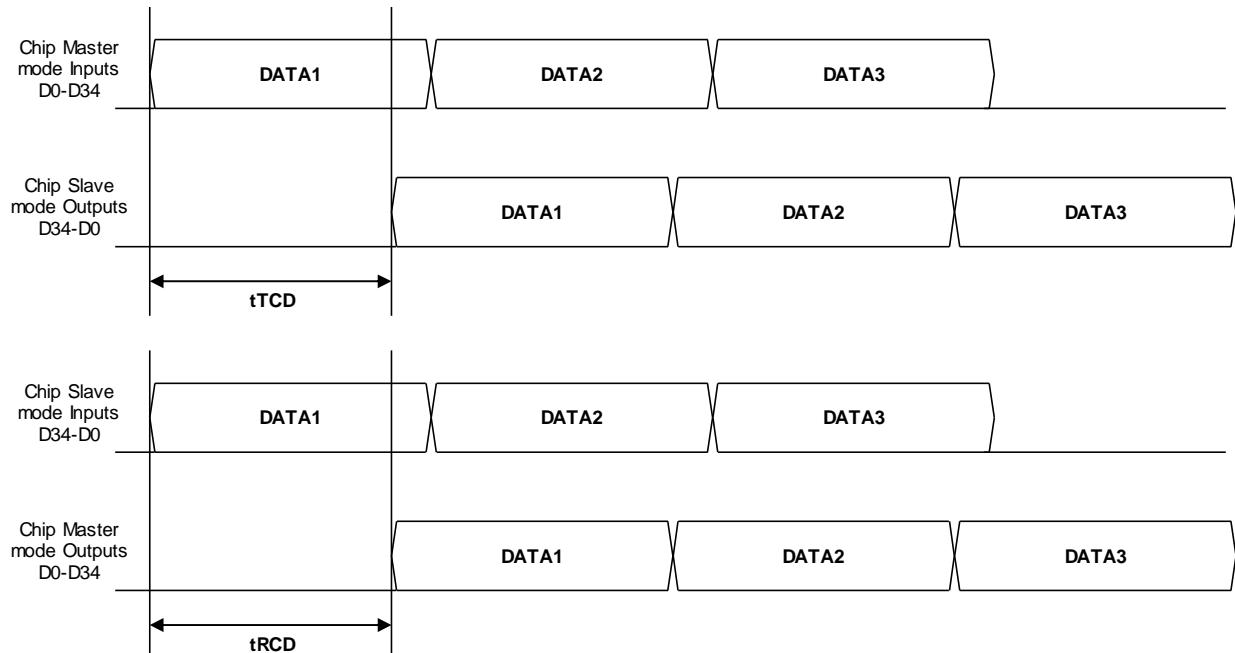


Figure 3 GPIO Input to Output delay timing diagram

**5.4. CML DC characteristics**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
VTOD	CML differential output peak to peak signal	-	600	800	1000	mVpp
VTOC	CML common mode output voltage	-	-	1200 - 0.5 VTOD	-	mV
ITOH	CML output leak current high	RESETN=0 TXP/N=CAPINA	-30	-	30	uA
ITOS	CML output short current	RESETN=0 TXP/N=0V	-80	-	-	mA
VRTH	CML differential input high threshold	-	-	-	50	mV
VRTL	CML differential input low threshold	-	-50	-	-	mV
IRIH	CML input leak current high	RESETN=0 RXP/N=CAPINA	-10	-	10	uA
IRIL	CML input leak current low	RESETN=0 RXP/N=0V	-10	-	10	uA
IRRIH	CML input current high	RXP/N=CAPINA	-	-	2	mA
IRRIL	CML input current low	RXP/N=0V	-6	-	-	mA
RRIN	CML differential input resistance	-	80	100	120	$\Omega$

**5.5. CML AC characteristics**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
tTRF	CML output rise and fall time (20%-80%)	-	50	-	150	ps
tTPLL0	RESETN=1 to CML output delay	-	-	-	10	ms
tTPLL1	RESETN=0 to CML output high fix delay	-	-	-	500	ns
tTNPO	READY low to training pattern output delay	-	-	-	100	us
tTBIT	Output unit interval	DATA_WIDTH=0 DATA_WIDTH=1	- -	tDCP÷30 tDCP÷50	- -	ns ns
tRBIT	Input unit interval	-	250	-	2222	ps
tRPLL0	Training pattern input to LOCKN low delay	Unidirectional mode	-	-	10	ms
tRPLL1	RESETN low to LOCKN High delay	Unidirectional mode	-	-	10	us
tRLCK0	LOCKN low to data output delay	Unidirectional mode	-	-	5	ms

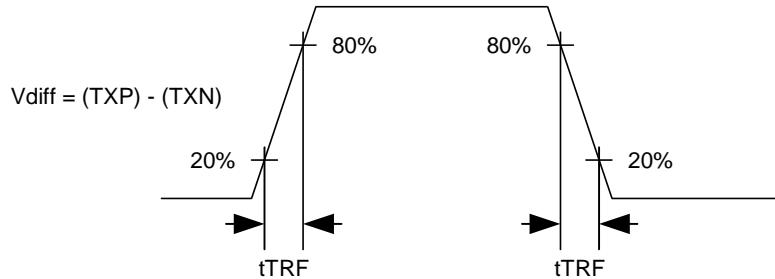
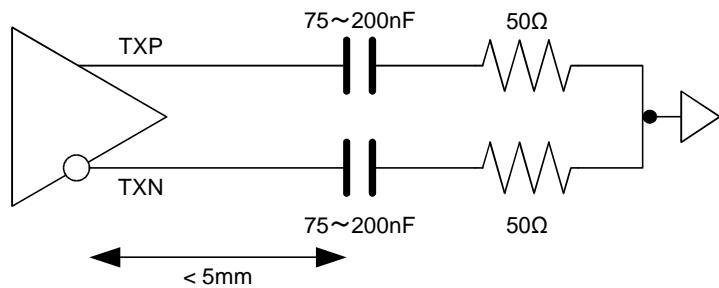


Figure 4 CML output AC characteristics diagram

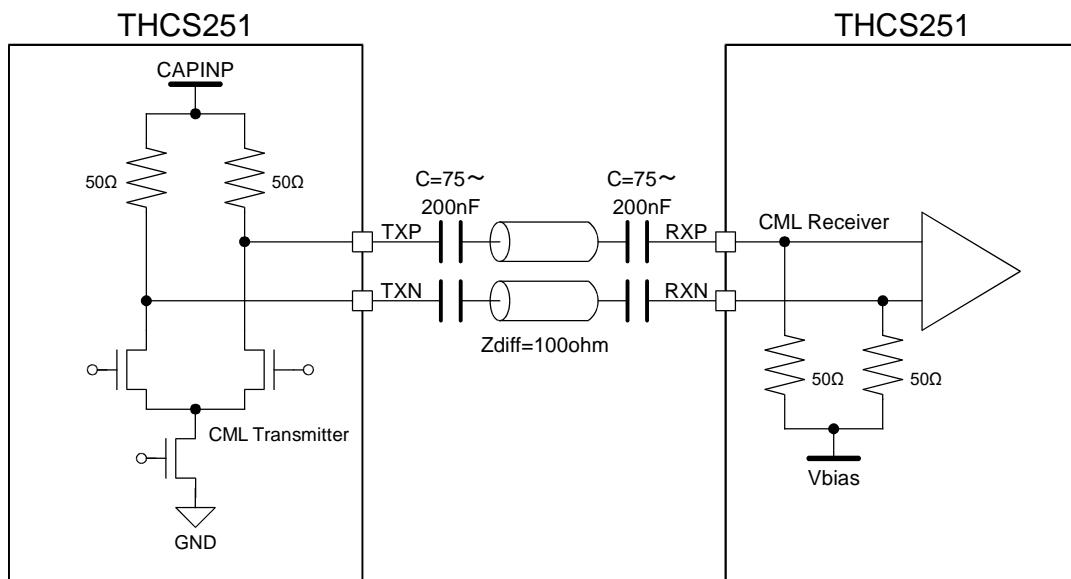


Figure 5 CML buffer equivalent circuit

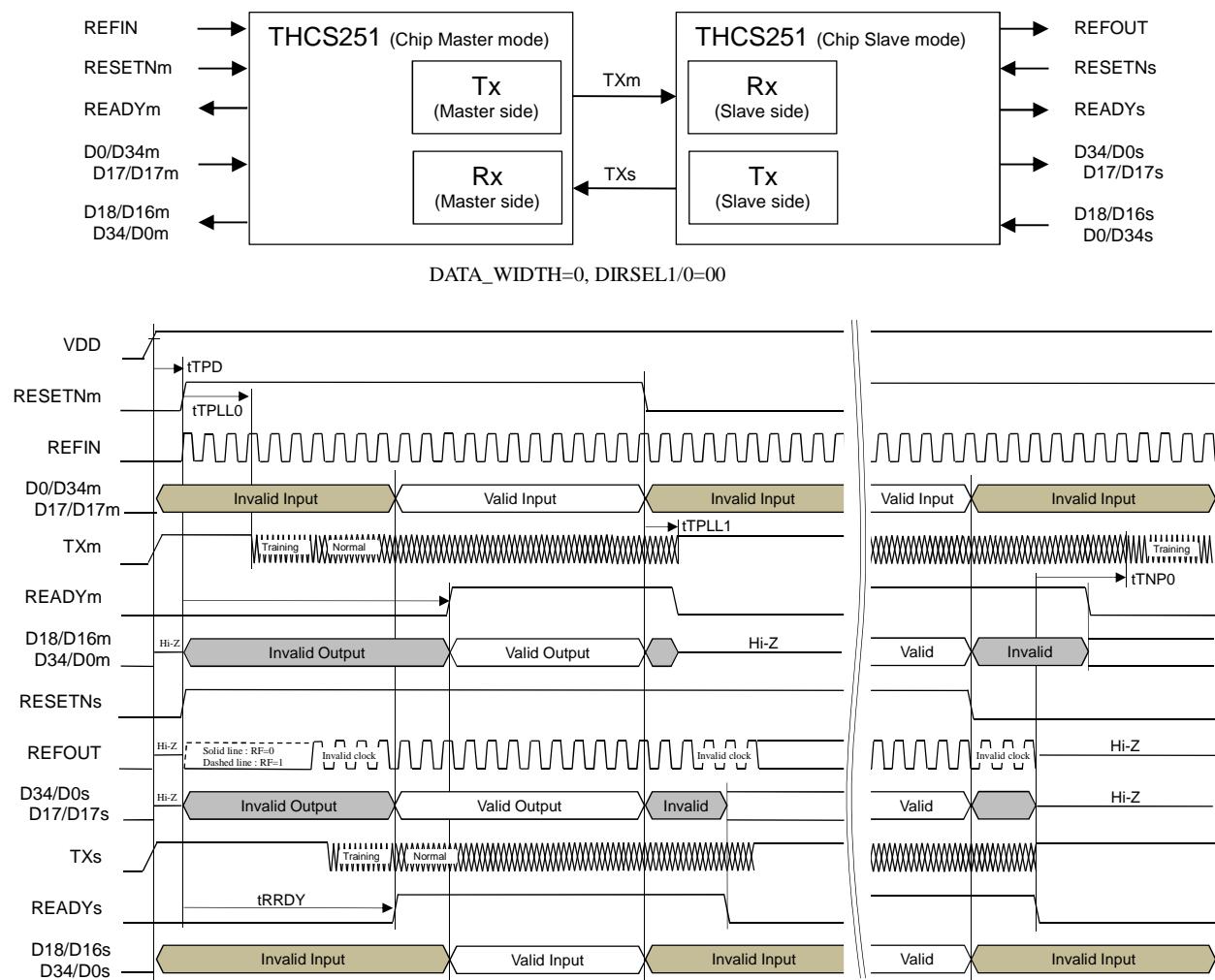


Figure 6 GPIO/CML Bi-directional mode Power on &amp; Reset timing diagram

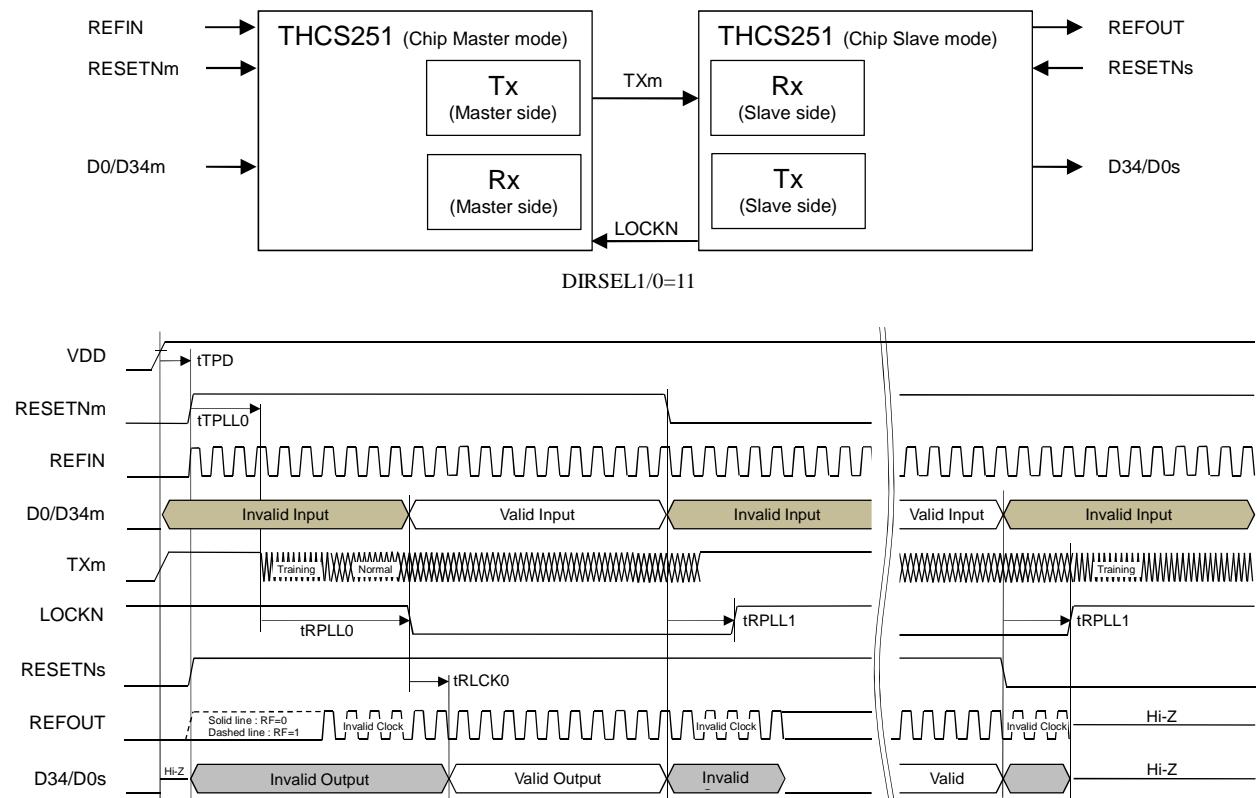


Figure 7 GPIO/CML Unidirectional mode lock &amp; unlock timing diagram

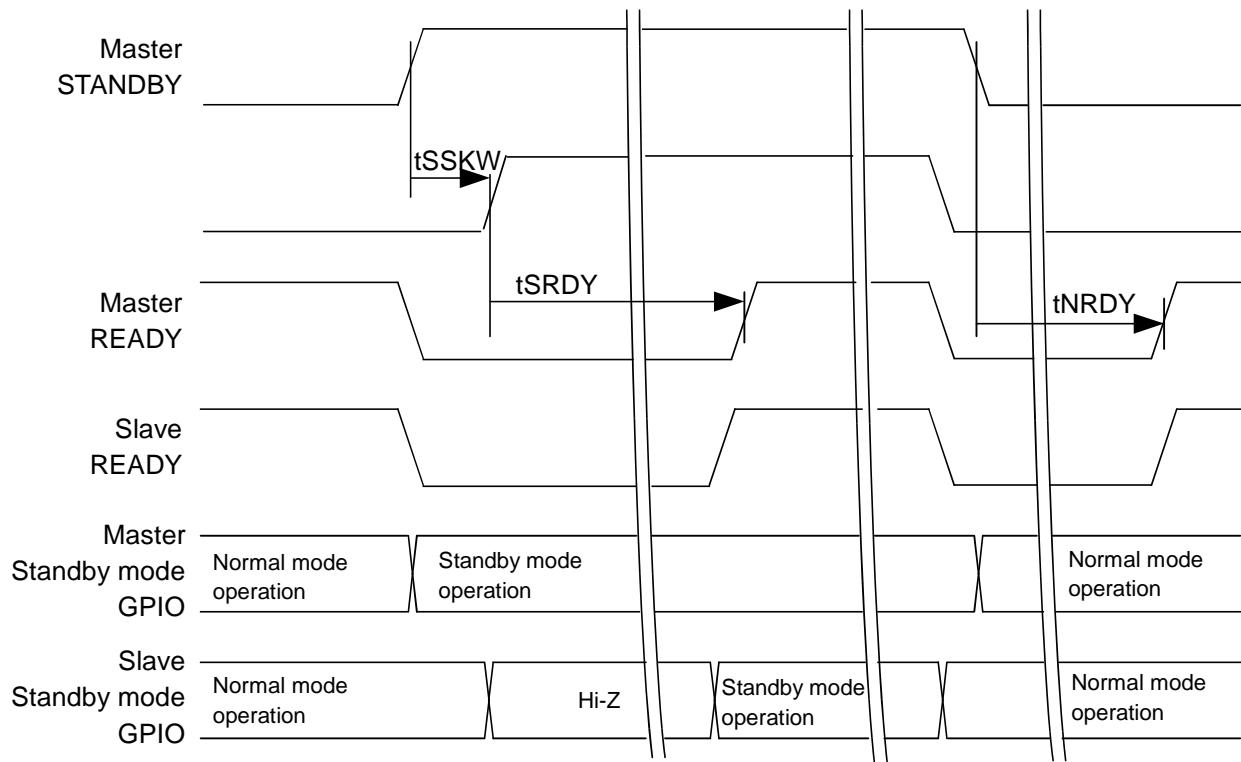
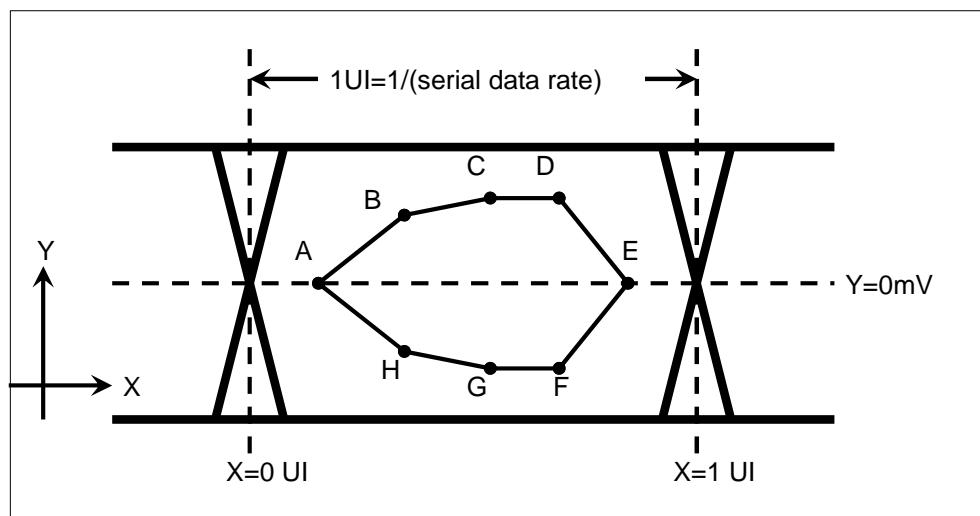


Figure 8 Standby mode timing diagram

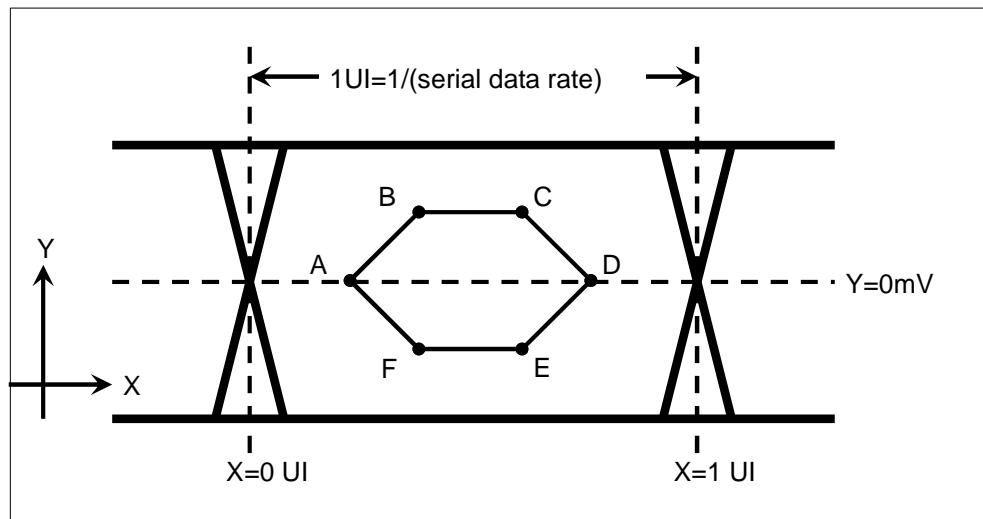
## 6. CML Line Eye diagrams

### 6.1. CML output Eye diagrams



	X[UI]	Y[mV]
A	0.15	0
B	0.355	140
C	0.5	175
D	0.645	175
E	0.85	0
F	0.645	-175
G	0.5	-175
H	0.355	-140

## 6.2. CML input Eye diagrams



	X[UI]	Y[mV]
A	0.25	0
B	0.3	50
C	0.7	50
D	0.75	0
E	0.7	-50
F	0.3	-50

## 7. Function

### 7.1. Functional overview

With high speed CML Serializer and Deserializer integrated onto a single chip, THCS251 enables Aggregation/Deaggregation up to 35-bits parallel General-Purpose I/O (GPIO) signal through full-duplex communication by two pairs of differential signal with minimal external components. THCS251 supports up to 8-bits low speed GPIO signal in low power Standby mode. It does not require any external clock generators e.g. a crystal oscillator. A pair of THCS251 enables to monitor and control peripheral devices via GPIOs. In case communication errors occur, they keep the GPIO signals and report by an interrupt signal.

### 7.2. Power supply

#### 7.2.1. Internal regulator output/input function (CAPOUT, CAPINA, CAPINP)

An internal regulator produces 1.2V (CAPOUT) only for internal use. It shall not be used for any other external loads. Bypass CAPOUT to GND with 10uF as a power supply pin. Bypass AVDD to GND with >10uF.

CAPINP and CAPINA supply reference voltage for internal analog circuits. Bypass CAPINP/CAPINA to GND with 0.1uF as power supply pins to reduce high frequency noise. CAPOUT, CAPINA and CAPINP must be tied together as Figure 9.

It is recommended to place ferrite bead for AVDD pins to reduce noise as Figure 9.

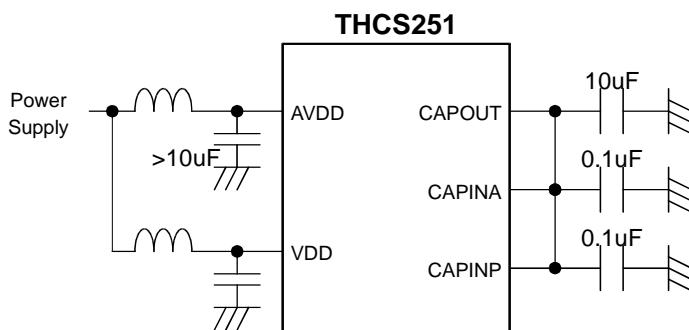


Figure 9 Connection of CAPOUT, CAPINA, CAPINP and decoupling capacitor

### 7.3. Operating mode

Table 1 shows operating mode setting.

Table 1 Operating mode setting

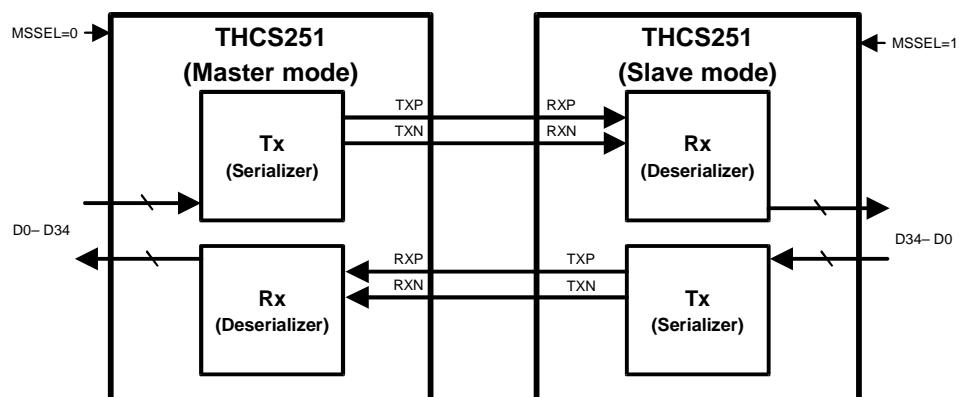
Operating mode	Setting		description
	RESETN	STANDBY	
Reset	0	-	Chip reset All outputs are Hi-Z
Normal	1	0	Normal operating mode
Standby	1	1	Low power and low frequency sampling rate transmission through up to 8-bits GPIO.

## 7.4. Transmission mode

THCS251 has a Bi-directional transmission mode with full-duplex communication and a Unidirectional communication mode.

### 7.4.1. Full duplex Bi-directional transmission mode

THCS251 can be used a pair of Master mode and Slave mode. Master mode samples data by external reference clock or internal oscillator clock. Slave mode samples data by CDR (Clock Data Recovery) clock generated by Rx. Same configuration of MSSEL between Master mode and Slave mode is prohibited. See Figure 10.



**Figure 10** Setting for Bi-directional transmission mode

**Table 2 Common setting of Master/Slave mode for Full duplex mode**

Use case		A-1	A-2	A-3	B-1	B-2	B-3	
Setting	DATA_WIDTH	0	0	0	1	1	1	
Mode	DIRSEL1, DIRSEL0	00	01	10	00	01	10	
	Downstream bit count	18	21	14	24	30	34	
	Upstream bit count	17	14	21	11	5	1	
	CML line data rate	External reference clock mode: 1/tTCP x 30 Internal oscillator clock mode: 1/tOSC x 30			External reference clock mode: 1/tTCP x 50 Internal oscillator clock mode: 1/tOSC x 50			
Data pin for Master mode	D0/D34	=>	=>	=>	=>	=>	=>	D34/D0
	D1/D33	=>	=>	=>	=>	=>	=>	D33/D1
	D2/D32	=>	=>	=>	=>	=>	=>	D32/D2
	D3/D31	=>	=>	=>	=>	=>	=>	D31/D3
	D4/D30	=>	=>	=>	=>	=>	=>	D30/D4
	D5/D29	=>	=>	=>	=>	=>	=>	D29/D5
	D6/D28	=>	=>	=>	=>	=>	=>	D28/D6
	D7/D27	=>	=>	=>	=>	=>	=>	D27/D7
	D8/D26	=>	=>	=>	=>	=>	=>	D26/D8
	D9/D25	=>	=>	=>	=>	=>	=>	D25/D9
	D10/D24	=>	=>	=>	=>	=>	=>	D24/D10
	D11/D23	=>	=>	=>	=>	=>	=>	D23/D11
	D12/D22	=>	=>	=>	=>	=>	=>	D22/D12
	D13/D21	=>	=>	=>	=>	=>	=>	D21/D13
	D14/D20	=>	=>	<=	=>	=>	=>	D20/D14
	D15/D19	=>	=>	<=	=>	=>	=>	D19/D15
	D16/D18	=>	=>	<=	=>	=>	=>	D18/D16
	D17/D17	=>	=>	<=	=>	=>	=>	D17/D17
	D18/D16	<=	=>	<=	=>	=>	=>	D16/D18
	D19/D15	<=	=>	<=	=>	=>	=>	D15/D19
	D20/D14	<=	=>	<=	=>	=>	=>	D14/D20
	D21/D13	<=	<=	<=	=>	=>	=>	D13/D21
	D22/D12	<=	<=	<=	=>	=>	=>	D12/D22
	D23/D11	<=	<=	<=	=>	=>	=>	D11/D23
	D24/D10	<=	<=	<=	<=	=>	=>	D10/D24
	D25/D9	<=	<=	<=	<=	=>	=>	D9/D25
	D26/D8	<=	<=	<=	<=	=>	=>	D8/D26
	D27/D7	<=	<=	<=	<=	=>	=>	D7/D27
	D28/D6	<=	<=	<=	<=	=>	=>	D6/D28
	D29/D5	<=	<=	<=	<=	=>	=>	D5/D29
	D30/D4	<=	<=	<=	<=	<=	=>	D4/D30
	D31/D3	<=	<=	<=	<=	<=	=>	D3/D31
	D32/D2	<=	<=	<=	<=	<=	=>	D2/D32
	D33/D1	<=	<=	<=	<=	<=	=>	D1/D33
	D34/D0	<=	<=	<=	<=	<=	<=	D0/D34

“=>” means Downstream (GPIO input in Master mode and GPIO output in Slave mode).

“<=” means Upstream (GPIO input in Slave mode and GPIO output in Master mode).

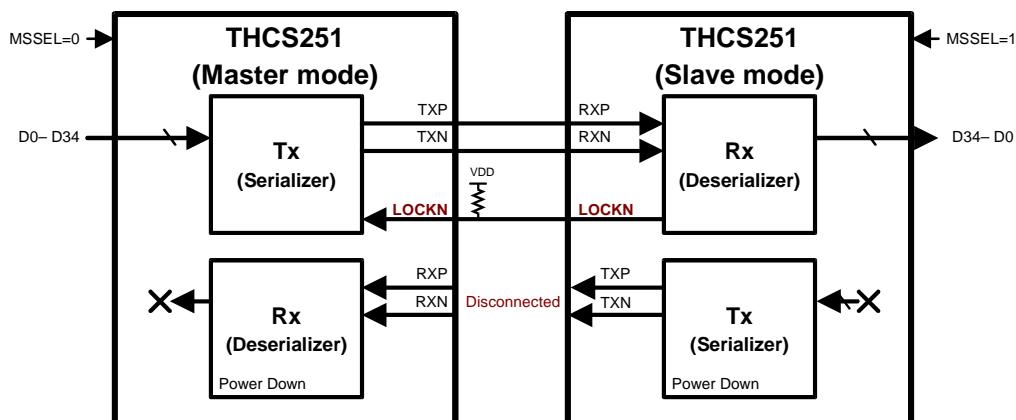
Start communication after setting each "Use case" in both Master/Slave.

#### 7.4.2. Unidirectional transmission mode

THCS251 operates in Unidirectional transmission mode by setting DIRSEL1=1 and DIRSEL0=1. A pair of differential signal from Slave mode to Master mode shall not be connected. LOCKN connection from Slave mode to Master mode is required.

**Table 3 INT/LOCKN function in Unidirectional transmission mode**

Setting			LOCKN	Description
DIRSEL1	DIRSEL0	MSSEL		
1	1	0	LOCKN Input	Master mode
		1	LOCKN Output (open-drain)	Slave mode



**Figure 11 Setting for Unidirectional transmission mode**

**Table 4 Common setting of Master/Slave mode for Unidirectional transmission mode**

Use case		U-1	U-2		
Setting	DATA_WIDTH	0	1		
	Downstream bit count	22	35		
	Upstream bit count	0	0		
Mode	CML line data rate	External reference clock mode: 1/tTCIP x 30 Internal oscillator clock mode: 1/tOSC x 30	External reference clock mode: 1/tTCIP x 50 Internal oscillator clock mode: 1/tOSC x 50		
Data pin for Master mode	D0/D34 - D21/D13 - D22/D12 - D34/D0	=>	=>	D34/D0 - D13/D21 - D12/D22 - D0/D34	Data pin for Slave mode

“=>” means Downstream (GPIO input in Master mode and GPIO output in Slave mode).

Start communication after setting each “Use case” in both Master/Slave.

## 7.5. IO configuration

### 7.5.1. Input and Output digital noise filter

THCS251 has digital noise filters for GPIO input (for CMOS input noise immunity) and output (for CML Line noise immunity) which are configured by setting FILTSEL1 and FILTSEL0 shown in Table 5 and Table 6. The data width less than (tap\_num - 1) tFLTCK is filtered. tap\_num is shown in Table 5 and Table 6.

**Table 5 Input digital noise filter setting**

FILTSEL1	FILTSEL0	Function	Filter number of taps (tap_num)
0	0	All digital noise filter setting	Disable
	1		4
1	0		8
	1		16

**Table 6 Output digital noise filter setting**

FILTSEL1	FILTSEL0	Function	Filter number of taps (tap_num)
0	0	All digital noise filter setting	Disable
	1		4
1	0		8
	1		16

### 7.5.2. LVC MOS output buffer type configuration

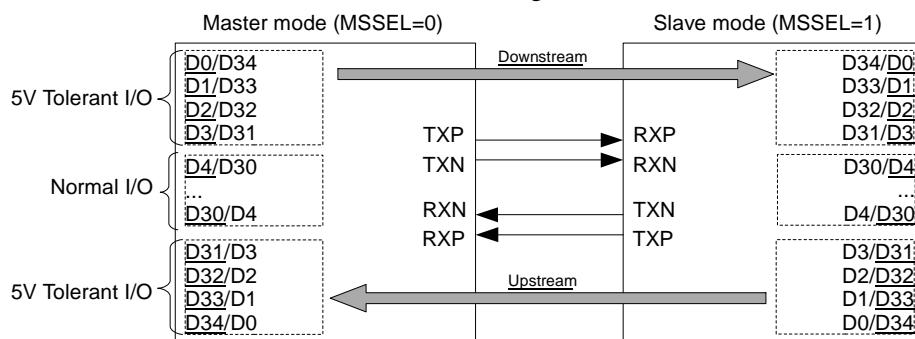
GPIO output buffer types are selectable from open-drain or push-pull by setting OBUF.

**Table 7 Output buffer type configuration**

Setting OBUF	Function
0	All GPIO outputs buffer type are selected to open-drain.
1	All GPIO outputs buffer type are selected to push-pull.

### 7.5.3. 5V Tolerant I/O

Figure 12 shows the 5V tolerant I/O. Master and Slave has eight 5V tolerant I/O each.



**Figure 12 5V tolerant I/O**

## 7.6. Sampling clock configuration

### 7.6.1. Sampling clock selection

GPIO sampling clock is always supplied from the Master mode and Master mode is selectable from internal oscillator clock or external reference clock input as shown in Figure 13, Table 8 and Table 9. Internal oscillator frequency is selectable from 20MHz, 40MHz or 80MHz.

Table 10 shows internal oscillator frequency and CML Line data rate. REFEN of Master mode and Slave mode shall be the same setting. GPIO data sampling clock of Slave mode is CDR clock from Rx.

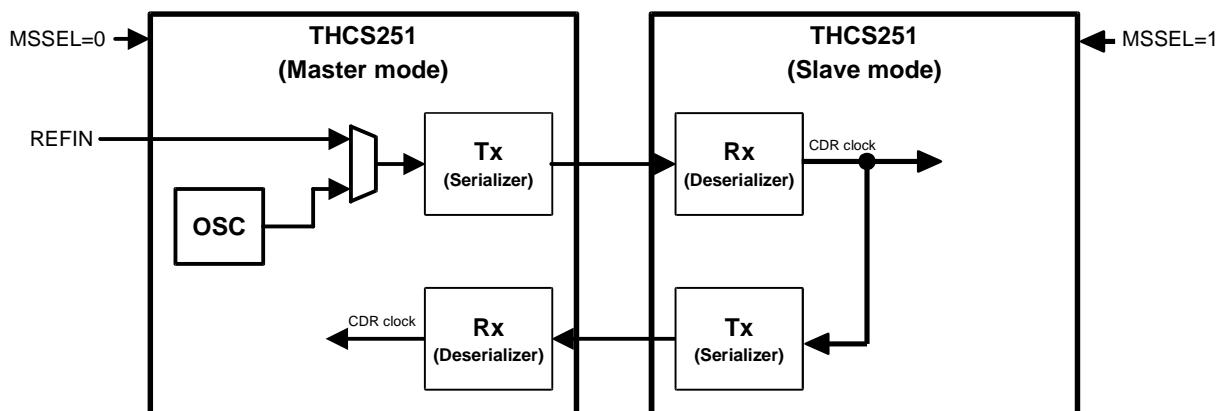


Figure 13 GPIO sampling clock source

Table 9 Sampling clock and REFIN/REFOUT/OSCSEL1 and RF/OSCSEL0 function

Setting		Sampling clock	REFIN/REFOUT/ OSCSEL1	RF/ OSCSEL0	Description
REFEN	MSSEL				
0	0 (Master mode)	Internal oscillator clock	Internal oscillator clock setting OSCSEL1, OSCSEL0		GPIO inputs are sampled by internal oscillator clock. Internal oscillator clock frequency is selected by setting of OSCSEL1 and OSCSEL0 (See Table 10)
	1 (Slave mode)	CDR clock	Hi-Z	- (Set to Low)	
1	0 (Master mode)	External reference clock	External reference clock input REFIN	Sampling clock edge selection RF	GPIO inputs are sampled by external reference clock
	1 (Slave mode)	CDR clock	CDR clock output REFOUT	GPIO output clock edge selection RF	

Table 10 Oscillator Clock Frequency and CML Line data rate

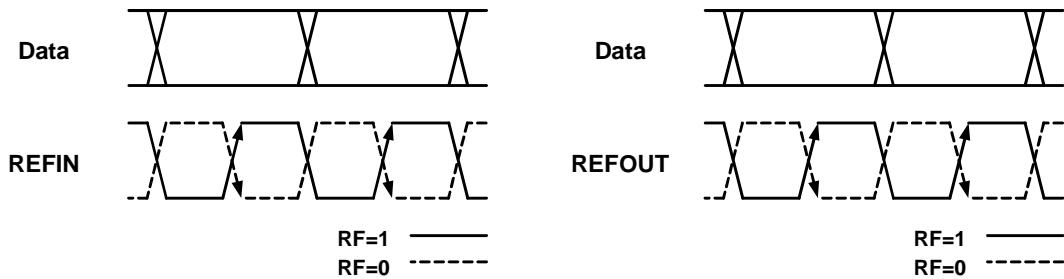
REFEN	MSSEL	Setting		Sampling frequency [ <sup>1</sup> ]	CML Line data rate <sup>[<sup>1</sup>]</sup>		Description
		OSCSEL1	OSCSEL0		DATA_WIDTH=0	DATA_WIDTH=1	
0	0 (Master mode)	0	0	20MHz	600Mbps	1Gbps	-
		0	1	-	-	-	Prohibition
		1	0	40MHz	1.2Gbps	2.0Gbps	-
		1	1	80MHz	2.4Gbps	Prohibition	-

\*1 Typical value, Spec is typical±20%

When REFEN=1, RF selects REFIN sampling clock edge of Master mode and REFOUT output clock edge of Slave mode.

**Table 11 RF Function**

Setting	Description	
RF	REFIN sampling edge	REFOUT output edge
0	Fall edge	Fall edge
1	Rise edge	Rise edge

**Figure 14 Input / Output clock edge**

### 7.6.2. Spread Spectrum Clock Generator (SSCG) and REFIN frequency

THCS251 CML serial data output, GPIO data output and clock output are modulated by integrated programmable SSCG. Only Master mode operates SSCG function. The SSCG is enabled by setting SSEN.

**Table 12 SSCG setting registers**

Setting		Description
SSEN		
0		SSCG is off.
1		SSCG is on and fixed setting. Modulation rate is $\pm 0.5\%$ . Modulation frequency is 12kHz when $f_{CLKSSCG} = FREF = 20MHz$ . ( 20MHz / 1664 ) = 12kHz )

**Table 13 f<sub>CLKSSSG</sub>**

Setting			Sampling clock	Sampling clock frequency	f <sub>CLKSSCG</sub>
REFEN	OSCSEL1	OSCSEL0			
0	0	0	Internal oscillator clock	Low	FREF <sup>[*1]</sup>
	0	1		-	-
	1	0		Low	FREF <sup>[*1]</sup>
	1	1		High	FREF <sup>[*1]</sup> /2
1	-	-	External reference clock input REFIN	15 – 57MHz	FREF <sup>[*1]</sup>

\*1 FREF : Sampling clock frequency

**Table 14 External reference clock input frequency range and SSCG setting**

Setting		External reference clock input frequency range [MHz]	CML Line multiply ratio	CML Line data rate [Gbps]	SSCG
DATA_WIDTH	SSEN				
0	0	15 - 100	x30	0.45 - 3.0	Disable
	1	15 - 57	x30	0.45 - 1.71	Enable
1	0	9 - 80	x50	0.45 - 4.0	Disable
	1	9 - 32.5	x50	0.45 - 1.625	Enable

### 7.7. Error detection and indication

THCS251 has READY and INT for indicating Link status of CML Line communication.

READY indicates establishment of communication for GPIOs. INT indicates CML Link communication error.

**Table 15 READY and INT**

Status		Description
READY	INT [*1]	
0	1 (pull-up)	CML Link communication unlock state GPIO cannot transmit
1	0	CML Link communication lock state Bit level error occurred
	1 (pull-up)	CML Link communication lock state No error

\*1 INT buffer type is open-drain. “1” output means pull-up.

### 7.8. Standby mode

THCS251 operates in Standby mode by setting STANDBY=1. The Standby mode is low power consumption and low frequency sampling rate transmission mode. In Standby mode, THCS251 can transmit up to 8-bits GPIO through handshake communication between Master mode and Slave mode. Polling period is 100ms.

READY is also enabled in Standby mode. When handshake communication is completed, READY goes from low to high.

The GPIO pins shown in Table 16 are configured to Downstream, Upstream or Static state. On the other hand D4/D30 - D30/D4 are fixed to Static state as Hi-Z.

**Table 16 Standby mode direction setting**

D0/D34	=>	D34/D0	Data Pin for Slave mode
D1/D33	=>	D33/D1	
D2/D32	=>	D32/D2	
D3/D31	=>	D31/D3	
D4/D30 - D30/D4	Static	D30/D4 - D4/D30	
D31/D3	<=	D3/D31	
D32/D2	<=	D2/D32	
D33/D1	<=	D1/D33	
D34/D0	<=	D0/D34	

“=>” means Downstream (GPIO input in Master mode and GPIO output in Slave mode).

“<=” means Upstream (GPIO input in Slave mode and GPIO output in Master mode).

“Static” means GPIO pins are Static state.

## 8. Package

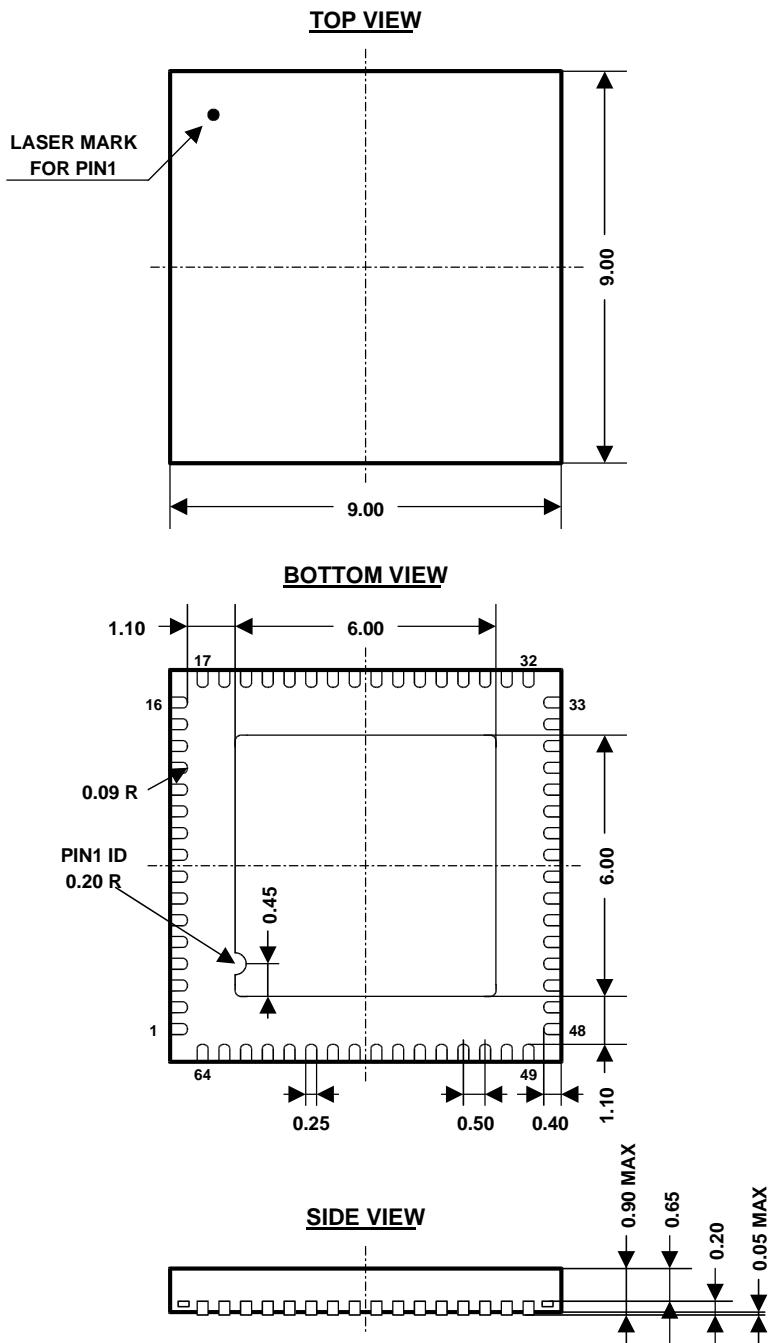


Figure 15 64-pin QFN package physical dimension

Unit : mm

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