

Features

- 3.3 and 5 VDC voltage supply option
- PWM Absolute Position
- Bushing or servo mount
- Non-contacting magnetic technology
- Small size
- CMOS and TTL compatible

- Resolution: 1024 states
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

EMS22P - Non-Contacting PWM Encoder

Electrical Characteristics	
Resolution	1024 states
nsulation Resistance (500 VDC)	1,000 megohm
Electrical Travel	
Supply Voltage	5.0 VDC ±10 %, 3.3 VDC ±10 %
,	
Dutput Voltage	
	Vss+0.4 V maximun
•	Vdd-0.5 V minimun
Output Current	vuu-0.5 v miiliinun
·	4 mA maximun
11 7 0	
	500 ns maximur
	10,000 rpm maximur
•	
Accuracy	
	±0.7 ° or bette
Worst Case	±1.4
Output Transition Noise	
Environmental Characteristics	
	-40 °C to +125 °C (-40 °F to +257 °F
	55 °C to +125 °C (-67 °F to +257 °F
•	
	50 C
Rotational Life	400 000 000
P Hating	IP 6
Mechanical Characteristics	
Nechanical Angle	360 ° Continuous
Starting	
Running	
Mounting Torque	
•	
•	
S .	Axial, radial or ribbon cable
	Axiai, radiai di fibboti cabi
Soldering Condition	00 50-10 04-10 50
Manual Soldering	
	370 °C (700 °F) max. for 3 second
Wave Soldering	96.5Sn/3.0Ag/0.5Cu solder with no-clean flu
	000 00 (E00 0E) (100 1
	260 °C (500 °F) max. for 10 second
Wash processes	260 °C (500 °F) max. for 10 second
Marking	260 °C (500 °F) max. for 10 seconds

Pin Configuration

Output Type	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6
PWM	PWM Signal	GND	GND	GND	VCC*	CS**

- * Can be 5 or 3.3 VDC depending on the version.
- ** Active low chip select pin; if not used connect pin 6 to GND.



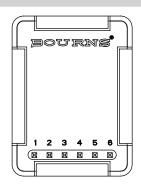
WARNING Cancer and Reproductive Harm - www.P65Warnings.ca.gov

*RoHS Directive 2015/863, Mar 31, 2015 and Annex.

Specifications are subject to change without notice.

Users should verify actual device performance in their specific applications.

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Applications

- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

- Medical (low/medium risk)*
- Office equipment
- Audio and broadcast equipment

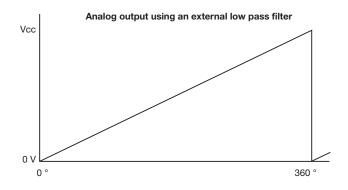
EMS22P - Non-Contacting PWM Encoder

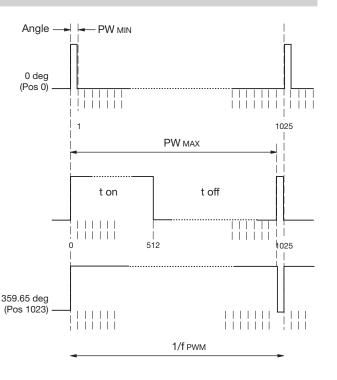
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Output Type Waveform and Variant Table

PWM Output

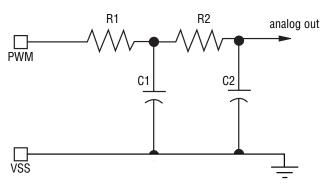
Parameter	Symbol	Туре	Unit	Note
PWM frequency	fPWM	0.9756	KHz	Signal period: 1025 μs
MIN pulse with	PWMIN	1	μS	Position 0 Angle 0 °
MAX pulse with	PWMAX	1024	μS	Position 1023 Angle 359.65 °





Position = t on * 1025/(t on + t off) - 1

Recommended Filter



Simple Passive 2nd Order Low Pass Filter

R1, R2 ≥ 4.7K Ohms

C1, C2 \geq 1 μ F / 6 V

R1 should be \geq 4.7K ohms to avoid loading of the PWM output. Larger values of Rx and Cx will provide better filtering and less ripple, but will also slow down the response time.

Users should verify actual device performance in their specific applications.

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Consult factory for options not shown, including:

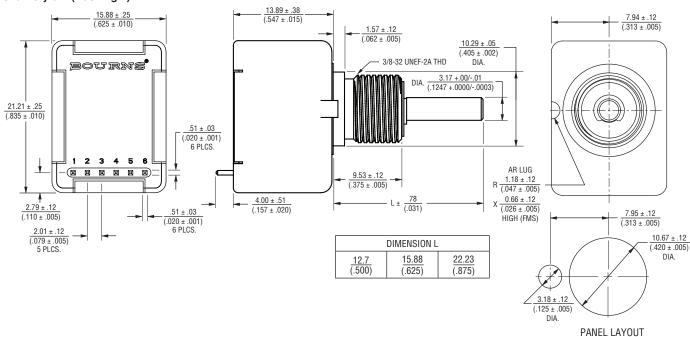
- Wire lead or cable options Special shaft/bushing sizes and features
- Connectors
- Special performance characteristics
- Non-standard resolutions PCB mounting bracket

EMS22P - Non-Contacting PWM Encoder

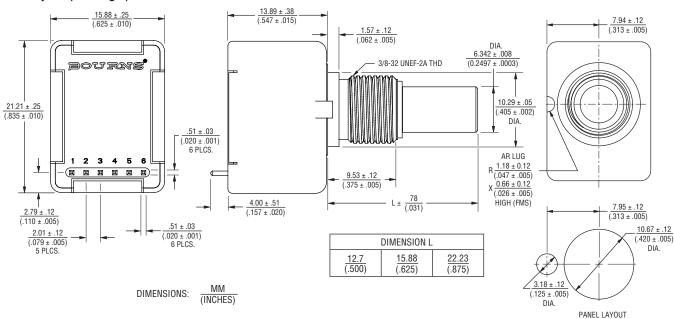
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Product Dimensions

Shaft Style D (Bushing T)



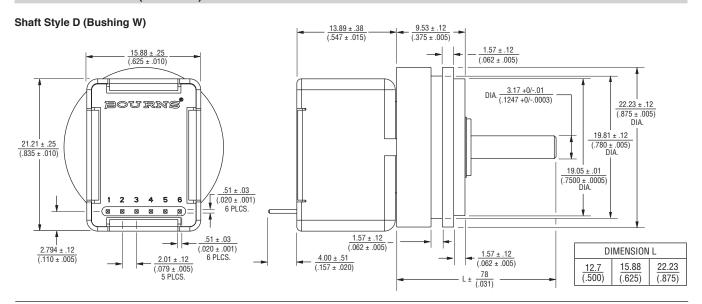
Shaft Style B (Bushing S)

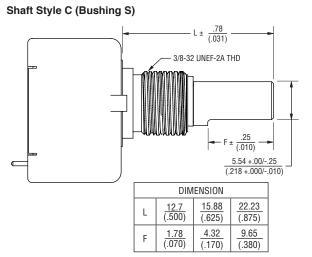


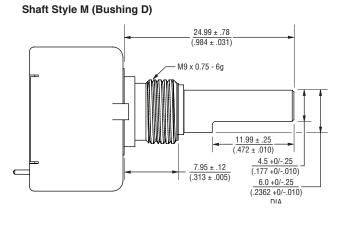
EMS22P - Non-Contacting PWM Encoder

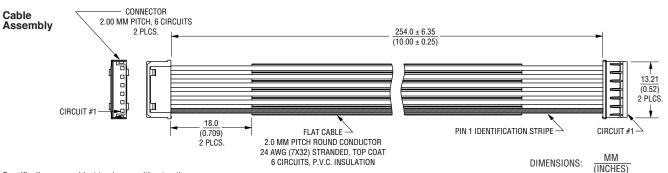
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Product Dimensions (Continued)





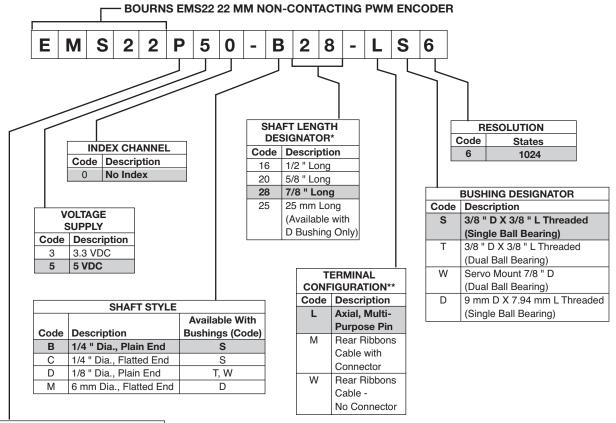




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How To Order



OUTPUT TYPE				
Code	Description	Notes		
Р	CW PWM	See Note 1		
R	CCW PWM	See Note 2		

^{*} Shaft length measured from mounting surface.

Note 1: (P) t on increases from 1 to 1025 with CW rotation of the shaft.

Note 2: (R) t on increases from 1 to 1025 with CCW rotation of the shaft.

^{**} Standard ribbon cable is 10 inches long. Consult factory for other lengths.

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