# **TFS757-764HG HiperTFS**<sup>™</sup> Family



# Combined Two-Switch Forward and Flyback Power Supply Controllers with Integrated High Voltage MOSFETs

# Key Benefits

- Single chip solution for two-switch forward main and flyback standby
- High integration allows smaller form factor and higher power density designs
  - Incorporates control, gate drivers, and three power MOSFETS
  - · Level shift technology eliminates need for pulse transformer
- Protection features include: UV, OV, OTP, OCP, and SCP
  Transformer reset control
- Prevents transformer saturation under all conditions
- Allows >50% duty cycle operation
- Reduces primary side RMS currents and conduction losses
- Standby supply provides built-in overload power compensation
- Up to 434 W total output power in a highly compact package
  Up to 550 W peak
  - High efficiency solution easily enables design to meet stringent efficiency specifications
  - >90% efficiency at full load
  - No-load regulation and low losses at light-load
- Simple clip mounting to heat sink without need for insulation pad
- Halogen free and RoHS compliant

# Applications

- PC
- Printer
- LCD TV
- Video game consoles
- High-power adapters
- · Industrial and appliance high-power adapters

# **Output Power Table**

Product	Two-	Two-Switched Forward 380 V					
	Continuous (25 °C)	Continuous (50 °C)	Peak (50 °C)	50 °C			
TFS757HG	193 W	163 W	228 W	20 W			
TFS758HG	236 W	200 W	278 W	20 W			
TFS759HG	280 W	235 W	309 W	20 W			
TFS760HG	305 W	258 W	358 W	20 W			
TFS761HG	326 W	276 W	383 W	20 W			
TFS762HG	360 W	304 W	407 W	20 W			
TFS763HG	388 W	327 W	455 W	20 W			
TFS764HG	414 W	344 W	530 W	20 W			

Table 1. Output Power Table (See Notes on page 13).



Figure 1. Simplified Schematic of Two-Switch Forward and Flyback Converter.

# Section List

Description	3
Product Highlights	З
Pin Functional Description Pin Configuration Functional Block Diagram	5
Pin Configuration	5
Functional Block Diagram	6-7
Functional Description	8
Output Power Table	
Design, Assembly, and Layout Considerations	14
Application Example	
Absolute Maximum Ratings	
Parameter Table	
Typical Performance Characteristics	
Package Details	
Part Ordering Information	
Part Marking Information	



# Description

The HiperTFS device family members incorporate both a high-power two-switch-forward converter and a mid-power flyback (standby) converter into a single, low-profile eSIP™ power package. The single chip solution provides the controllers for the two-switch-forward and flyback converters, high- and low-side drivers, all three of the high-voltage power MOSFETs, and eliminates the converter's need for costly external pulse transformers. The device is ideal for high power applications that require both a main power converter (two-switch forward) up to 414 W, and standby converter (flyback) up to 20 W. HiperTFS includes Power Integrations' standard set of comprehensive protection features, such as integrated soft-start, fault and over-load protection, and hysteretic thermal shutdown. HiperTFS utilizes advanced power packaging technology that simplifies the complexity of two-switch forward layout, mounting and thermal management, while providing very high power capabilities in a single compact package. The devices operate over a wide input voltage range, and can be used following a power-factor correction stage such as HiperPFS.

Two-switch-forward power converters are often selected for applications demanding cost-effective efficiency, fast transient response, and accurate tolerance to line voltage fluctuation. The two-switch-forward controller incorporated into HiperTFS devices improves on the classic topology by allowing operation considerably above 60% duty cycle. This improvement reduces RMS currents conduction losses, minimizes the size and cost of the bulk capacitor, and minimizes output diode voltage ratings. The advanced design also includes transformer flux reset control (saturation protection) and charge-recovery switching of the high-side MOSFET, which reduces switching losses. This combination of innovations yields an extremely efficient power supply with smaller MOSFETs, fewer passives and discrete components, and a lower-cost transformer.

HiperTFS's flyback standby controller and MOSFET solution is based on the highly popular TinySwitch<sup>™</sup> technology used in billions of power converter ICs due to its simplicity of operation, light load efficiency, and rugged, reliable, performance. This flyback converter can provide up to 20 W of output power and the built in overload power compensation reduces component design margin.

# **Product Highlights**

#### Protected Two-Switch Forward and Flyback Combination Solution

- Incorporates three high-voltage power MOSFETs, main and standby controllers, and gate drivers
- Level shift technology eliminates need for pulse transformer
- Programmable line undervoltage (UV) detection prevents turn-off glitches

- Programmable line overvoltage (OV) detection; latching and non-latching
- Accurate hysteretic thermal shutdown (OTP)
- Accurate selectable current limit (main and standby)
- Fully integrated soft-start for minimum start-up stress
- Simple fast AC reset
- Reduced EMI
  - Synchronized 66 kHz forward and 132 kHz flyback converters
  - Frequency jitter
- Eliminates up to 30 discrete components for higher reliability and lower cost

#### Asymmetrical Two-Switch Forward Reduces Losses

- Allows >50% duty cycle operation
- Reduces primary side RMS currents and conduction losses
- Minimizes the size and cost of the bulk capacitor
- Allows reduced capacitance or longer hold-up time
- Allows lower voltage output diodes
- Transformer reset control
  - Prevents transformer saturation under all conditionsExtends duty cycle to satisfy AC cycle drop out ride through
- Duty cycle soft-start with 115% current limit boost
  - Satisfies 2 ms ~ 20 ms start-up with large capacitance at output
- Remote ON/OFF function
- Voltage mode controller with current limit

## 20 W Flyback with Selectable Power Limit

- TinySwitch-III based converter
- Selectable power limit (10 W, 12.5 W, 15 W, or 20 W)
- Built-in overload power compensation
  - Flat overload power vs. input voltage
  - Reduces component stress during overload conditions
  - Reduces required design margin for transformer and output diode
- Output overvoltage (OV) protection with fast AC reset
- Latching, non-latching, or auto-restart
- · Output short-circuit protection (SCP) with auto-restart
- Output over-current protection (OCP)

#### Advanced Package for High Power Applications

- 434 W output power capability in a highly compact package
  Up to 550 W peak
- Simple clip mounting to heat sink
- Can be directly connected to heat sink without insulation pad
- Provides thermal impedance equivalent to a TO-220
- Heat slug connected to ground potential for low EMI
- Staggered pin arrangement for simple routing of board traces and high-voltage creepage requirements
- Single power package for two power converters reduces
   assembly costs layout size



Function	Typical Two-Switch Forward	HiperTFS	Advantages of HiperTFS
Nominal Duty Cycle	33%	45%	Wider duty cycle reduces RMS switch currents by 17%.
Maximum Duty Cycle	<50%	63%	Reduces R <sub>DS(ON)</sub> losses by 31%
Switch Current (RMS)	100%	83%	
Output Catch Diode	$V_{o} + V_{D}/D_{MAX}$	$V_{o} + V_{D}/D_{MAX}$	Lower losses. Wider $D_{MAX}$ lowers catch diode rating by (1-(50%/63%)) = 21% reduction in catch diode voltage rating
Clamp Voltage	Reset diodes from zero to V <sub>IN</sub>	Reset from zero to (V <sub>IN</sub> + 130)	With fast/slow diode combination, allows charge recovery to limit high-side C <sub>oss</sub> loss
Thermal Shutdown		118 °C Shutdown / 55 °C hysteresis	HiperTFS provides integrated OTP device protection
Current Sense Resistor	0.5 V drop (0.33 Ω at 300 W)	Sense resistor not required	Improved efficiency. MOSFET R <sub>DS(ON)</sub> sense eliminated need for sense resistor
High-Side Drive	Requires gate-drive transformer (high cost)	Built in high-side drive	Lower cost; component elimination. Removes high-cost gate-drive transformer (EE10 or toroid)
Component Count	Higher	Lower	Saves up to 50 components, depending on specification.
TinySwitch Overload Power Compensation vs. Input Voltage		Built-in compensation	Safer design; easier to design power supply. Flattens overload output power over line voltages
Package Creepage	TO-220 = 1.17 mm	eSIP16/12 = 2.3 mm/ 3.3 mm	HiperTFS meets functional safety spacing at package pins
Package Assembly	2 × TO-220 package, 2 × SIL (insulation)	1 Package	No SIL (insulation) pad required

Table 2. Summary of Differences Between HiperTFS and Other Typical High Power Supplies.



# **Pin Functional Description**

#### MAIN DRAIN (D) Pin

Drain of the low-side MOSFET transistor forward converter.

## STANDBY DRAIN (DSB) Pin

Drain of the MOSFET of standby power supply.

## GROUND (G) Pin

This pin gives a signal current path to the substrate of the low-side controller. This pin is provided to allow a separate Kelvin connection to the substrate of the low-side controller to eliminate inductive voltages that might be developed by high switching currents in the SOURCE pin. The GROUND pin is not intended to carrier high currents, instead it is intended as a voltage-reference connection only.

## SOURCE (S) Pin

SOURCE pin that is common to both the standby and main supplies.

## **RESET (R) Pin**

This pin provides information to limit the maximum duty cycle as a function of the current fed into the RESET pin during the off-time of the main converter MOSFET. This pin can also be pulled up to bypass to signal remote ON/OFF of the main converter only.

#### ENABLE (EN) Pin

This is the ENABLE pin for the standby controller. Prior to the start-up a resistor connected from ENABLE to BYPASS, can be detected to select one of several internal current limits.

## LINE-SENSE (L) Pin

This pin provides input bulk voltage line-sense function. This information is used by the undervoltage and overvoltage detection circuits for both main and standby. The pin can also be pulled up to BYPASS or be pulled down to SOURCE to implement a remote ON/OFF of both standby and main supplies simultaneously. The LINE-SENSE pin works in conjunction with the RESET pin to implement a duty-cycle limit function. Also the LINE-SENSE pin compensates the value of standby current limit so as to flatten the output overload response as a function of input voltage.

## FEEDBACK (FB) Pin

This pin provides feedback for the main two transistor forward converter. An increase in current sink from FEEDBACK pin to ground, will lead to a reduction in operating duty cycle. This pin also selects the main device current limit at start-up (in a similar manner to ENABLE pin).

#### BYPASS (BP) Pin

This is the decoupled operating voltage pin for the low-side controller. At start-up the bypass capacitor is charged from an internal device current source. During normal operation the capacitor voltage is maintained by drawing current from the low-side bias winding on the standby power supply. This pin is also used to implement remote ON/OFF for the main controller. This is done by driving extra current into the BYPASS pin when we want to turn-on the Main controller. The BYPASS pin also implements a latch-off function to disable standby and main when the BP pin current exceeds latching threshold. Latch is reset when LINE-SENSE pin falls below UV (off) standby threshold.

#### HIGH-SIDE OPERATING VOLTAGE (VDDH) Pin

This is the high-side bias (VDD) of approximately 11.5 V. This voltage is maintained with current from a high-side bias winding on the main transformer and/or from a bootstrap diode from the low-side standby bias supply.

#### HIGH-SIDE SOURCE (HS) Pin

SOURCE pin of the high-side MOSFET.

#### HIGH-SIDE DRAIN (HD) Pin

DRAIN pin of the high-side MOSFET. This MOSFET is floating with respect to low-side source and ground.



Figure 2. Pin Configuration.





Figure 3. Functional Block Diagram for Two-Switch Forward Converter.





Figure 4. Functional Block Diagram for Flyback/Standby Converter.



# **Functional Description**

The HiperTFS contains two switch-mode power supply controllers and associated low-side MOSFET's along with high-side driver and high-side MOSFET.

- The HiperTFS two-switch forward includes a controller along with low-side power MOSFET, high-side power MOSFET and high-side driver. This device operates in voltage mode (linear duty-cycle control) at fixed frequency (exactly half the operating frequency of the standby controller). The control converts a current input (FEEDBACK pin), to a duty-cycle at the open drain MOSFET MAIN DRAIN pin decreasing duty-cycle with increasing sourced current from the FEEDBACK pin.
- The HiperTFS flyback includes a controller and power MOSFET which is based on TinySwitch-III. This device operates in multi-level ON/OFF current limit control mode. The open drain MOSFET (STANDBY DRAIN pin) is turned on when the sourced current from the ENABLE pin is below the threshold and switching is disabled when the ENABLE pin current is above the threshold.

In addition to the basic features, such as the high-voltage start-up, the cycle-by-cycle current limiting, loop compensation circuitry, auto-restart and thermal shutdown, the HiperTFS main controller incorporates many additional functions that reduce system cost, increase power supply performance and design flexibility.

#### Main Converter General Introduction

The Main converter for the HiperTFS, is a two-switch forward converter (although the HiperTFS could be used with other two-switch topologies). This topology involves a low-side and high-side power MOSFET, both of which are switched at the same time. In the case of the HiperTFS, the low-side MOSFET is a 725 V MOSFET (with the substrate connected to the SOURCE pin). The high-side MOSFET is a 530 V MOSFET (with the substrate connected to the HIGH-SIDE DRAIN (HD) pin). As such the substrate of both low-side and high-side MOSFET's are tied to quiet circuit nodes (0 V and V<sub>IN</sub> respectively), meaning that both MOSFETs have electrically quiet substrates – good for EMI.

The low-side MOSFET has a very low C<sub>oss</sub> capacitance and thus can be hard-switched without performance penalty. Due to the external clamp configuration it is possible to substantially soft-switch the high-side MOSFET at high-loads (thus eliminating a large proportion of high-side capacitive switching loss) and improving efficiency. The higher breakdown voltage on the low-side MOSFET allows the transformer reset voltage to exceed the input voltage, and thus allow operation at duty cycles greater than 50%. Higher duty cycle operation leads to lower RMS switch currents and also lower output diode voltage-rating, both of which contribute to improved efficiency.

The HiperTFS also contains a high-side driver to control the high-side MOSFET. This internal high-side driver eliminates the need for a gate-driver transformer, an expensive component that is required for many other two-switch forward circuits.



Figure 5. Switching Frequency Jitter (Idealized V<sub>DRAIN</sub> Waveforms).

#### Main Start-Up Operation

Once the flyback (standby) converter is up and running, the main converter can be enabled by two functions. The first condition is that the BYPASS pin remote-on current must exceed the remote-on threshold  $(I_{\text{BP(ON)}})$ , provided by an external remote ON/OFF circuit. This current threshold has a hysteresis to prevent noise interference. Once the BYPASS remote-on has been achieved, the HiperTFS also requires that the LINE-SENSE pin current exceeds the UV Main-on ( $I_{L(MA-UVON)}$ ), which corresponds to approximately 315 VDC input voltage when using a 4 M $\Omega$  LINE-SENSE pin resistor. Once this LINE-SENSE pin threshold has been achieved the HiperTFS will enter a 12 ms pre-charge period ( $t_{\text{D/CHI}}$ ) to allow the PFC-boost stage to reach regulation before the main applies a load to the bulk-capacitor. Also during this pre-charge period the high-side driver is charged via the boot-strap diode from the low-side auxiliary voltage, and is charged when the main low-side MOSFET turns



Figure 6. Supply Start-Up Sequence by Remote ON.



on, while the main high-side MOSFET is held off. By the end of the pre-charge period, the PFC-boost voltage should be at or above the nominal boost voltage. The HiperTFS begins switching, going through the soft-start period ( $t_{ss}$ ). During the soft-start period the maximum duty cycle starts at 30% and is ramped during a 12 ms period to the maximum. The ramped duty cycle controls the rise slew rate of the output during start-up, allowing well controlled start-up and also facilitates a smooth transition when the control loop takes over regulation towards the end of soft-start. Also during a 32 ms period (starting at the beginning of soft-start), the main current limit is boosted to 115% of the nominal selected Main current. This allows the main to start-up within the required period for the application (typically < 20 ms for PC main applications), when there is a substantial capacitive load on the output. After the soft-start period, the current limit returns to 100% of the nominal selected current limit.

# Main Converter Control FEEDBACK (FB) Pin Operation

The FEEDBACK pin is the input for control loop feedback from the main control loop. During normal operation the FEEDBACK pin is used to provide duty cycle control for the main converter. The system output voltage is detected and converted into a feedback current. The main converter duty cycle will reduce as more current is sourced from the FEEDBACK pin, reaching zero duty cycle at approximately 2.1 mA. The nominal voltage of the FEEDBACK pin is maintained at approximately 3.5 V. An internal pole on the FEEDBACK pin is set to approximately 12 kHz, in order to facilitate optimal control loop response.

The maximum duty cycle of the main converter is defined by the LINE-SENSE pin and RESET pin behavior and is a dynamically calculated value according to cycle-by-cycle conditions on the LINE-SENSE pin and RESET pin.



Figure 7. PWM Duty Cycle vs. Control Current.

## Main High-Side Driver

The high-side driver is a device that is electrically floating at the potential of the HIGH-SIDE MOSFET SOURCE (HS) pin. This device provides gate-drive for the high-side Main MOSFET. The low-side main and high-side main MOSFET's switch simultaneously. The high-side driver has a HIGH-SIDE OPERATING VOLTAGE supply pin. External circuitry provides a current source into this HIGH-SIDE OPERATING VOLTAGE pin. The high-side operating voltage has an internal 12 V shunt-regulator. The device consumes approximately 2 mA when driving the high-side MOSFET.

The HIGH-SIDE OPERATING VOLTAGE pin has an undervoltage lock-out threshold, to prevent gate-drive when the supply voltage drops below a safe threshold. At power-up the high-side driver remains in the off-state, until the HIGH-SIDE OPERATING VOLTAGE pin is charged above 10.5 V, at which point the high-side driver becomes active. The high-side driver is initially charged via a boot-strap diode connected via a diode to the HIGH-SIDE OPERATING VOLTAGE pin from the low-side standby auxiliary supply (approximately 12 V). During start-up the high-side MOSFET remains off, but the low-side MOSFET is turned on for a period of 14 ms to allow pre-charge of the high-side operating voltage to 12 V. After this period, the highside operating voltage is supplied by a forward-winding coupled to the main transformer. This floating winding provides energy every time the main converter switches one cycle. The operating power for high-side operating voltage can also be provided from a floating winding on the standby supply. However this would continue delivering power even when the main converter is in remote-off, and thus is considered undesirable from a standby light-load efficiency point of view.

Once the high-side driver is operating it receives level-shifted drive commands from the low-side device. These drive commands cause both turn-on and turn-off drive of the high-side main MOSFET simultaneously with that of the low-side main MOSFET.

The high-side driver also contains a thermal shutdown on-chip, but this is set to a temperature above the thermal shutdown temperature of the low-side device. Thus the low-side will always shutdown first.

## Main Converter Maximum Duty Cycle

The LINE-SENSE pin resistor converts the input voltage into an LINE-SENSE pin current signal. The RESET pin resistor converts the reset voltage into an RESET pin current signal. The LINE-SENSE pin and RESET pin currents allow the HiperTFS to determine a maximum duty cycle envelope on a cycle-by-cycle basis. This feature ensures sufficient time for transformer reset on a cycle-by-cycle basis and also protects against single-cycle transformer saturation and at high-input voltage by limiting the maximum duty cycle to prevent the transformer from reaching an unsafe flux density during the on-time period. Both of these features allow the optimal performance to be obtained from the main transformer. The duty cycle limit is trimmed during production.

The LINE-SENSE pin and RESET pin are sampled just before the turn-on of the next main cycle. This is done to sample at a point when there is minimal noise in the system. Due to the low current signal input to the LINE-SENSE pin and RESET pin, care should be taken to prevent noise injection on these pins (see Applications section layout guidelines for details).

## Main On-Chip Current Limit with External Selection

During start-up, the FEEDBACK pin and ENABLE pin are both used to select internal current limits for the main and standby converters respectively. The detection period occurs at the initial start-up of the device, and before the main or standby MOSFETs start switching. This is done to minimize noise interference.





Figure 8. Duty Cycle Limit vs. Ratio of R Pin Current Over L Pin Current.

A resistor R<sub>FB</sub> is connected from the BYPASS pin to the FEEDBACK pin. This resistor feeds current into the FEEDBACK pin (who's voltage is clamped to approximately 1 V during this detection period). The current into the FEEDBACK pin is determined by the value of the resistor, and thus the input current (and indirectly the resistor value), select an internal current limit according to the following table.

I <sub>ғв</sub> (Threshold)	I <sub>LIMIT</sub>			R <sub>FB(SELECT)</sub> (1%)		
0.0-5.1 μA	L1	60%	mA	Open	kΩ	
5.1-11.9 μA	L2	80%	mA	511.0	kΩ	
11.9-23.8 μA	L3	100%	mA	232.0	kΩ	

Table 3. FEEDBACK Pin Main Current Limit Selection.



Figure 9. Current Limit Selection.

Main Line Undervoltage Detection (UV)

The LINE-SENSE pin resistor is connected to  $V_{\mbox{\tiny IN}}$  and generates a current signal proportional to  $V_{\ensuremath{\scriptscriptstyle \rm I\!N}}$  . The LINE-SENSE pin voltage is held by the device at 2.35 V. The LINE-SENSE pin current signal is used to trigger under/overvoltage thresholds for both the standby and main converters. Assuming a LINE-SENSE pin resistor of 4 M $\Omega$ , the standby will begin operating when the LINE-SENSE pin current exceeds the  $(I_{L(SB-UVON)})$  threshold, nominally approximately 100 V. However the main is still held in the off-state, until the LINE-SENSE pin current exceeds the  $(I_{\text{L(MA-UVON)}})$  threshold, nominally 315 V for 4 M $\Omega.~$  There is hysteresis for both main and standby undervoltage-off thresholds, to allow sufficient margin to avoid accidental triggering, and to provide sufficient margin to meet hold-up time requirements. Bear in mind that the main converter may start to loose regulation before it finally shuts down. This is because the dynamic duty cycle limit may clamp the duty cycle below that required for regulation at lower input voltages. Once the input voltage falls below the 215 V ( $I_{LIMA UVOFFI}$ ) threshold, the main will shutdown but standby will continue to operate. The standby will turn off when the input voltage drops below approximately 40 V (I<sub>L(SB-UVON)</sub>).





Figure 10. Main and Standby Start-Up.

#### Main Reset Overvoltage Detection

There is also an overvoltage threshold for the RESET pin. When triggered, the RESET overvoltage will shutdown only the Main, leaving the Standby in operation.



Figure 11. L and R Pin Duty Limit Mode.



#### **Standby Power General Introduction**

The standby is a wide range power supply, typically a flyback converter, operating over a wide input range (85-265 VAC) and delivering up to 20 W continuous output power. The standby power supply provides two functions in most high-power applications. It provides a direct secondary output but also provide bias power to other primary-side devices (in particular typically a PFC boost converter).

The HiperTFS standby retains most features of the TinySwitch-III, such as auto-restart, thermal shutdown, multi-level current limit ON/OFF control, etc. The HiperTFS standby controller has a few differences versus TinySwitch-III:

- 1. There are 4 current limits that are selected via the ENABLE pin (rather than by using different BYPASS pin capacitors as in TinySwitch-III). There are 4 user selectable current limits 500, 550, 650, 750 mA design for secondary standby output power of 10, 12.5, 15 and 20 W.
- Secondary OVP latching shutdown. This is triggered via a current in excess of the BYPASS pin latching shutdown threshold (I<sub>RP(SD)</sub> = 15 mA).
- 3. Dedicated LINE-SENSE pin for line-voltage detection providing absolute UV and OV ON/OFF thresholds (unlike TinySwitch-III which detects input voltage only during restart).
- 4. Current limit is compensated as a function of input voltage to maintain a flat overload characteristic versus input voltage.

In a high-power system, the standby power supply is the first power supply to begin operating. The main converter cannot begin working until the standby is in operation. Likewise the main converter will shutdown at a higher-voltage than the standby and thus the standby is always the last power supply to shutdown.

#### Standby On-Chip Current Limit with External Selection

During start-up, the FEEDBACK pin and ENABLE pin are both used to select internal current limits for the Main and Standby converters respectively. The detection period occurs at the initial start-up of the device (just after BYPASS pin voltage of 4.7 V is achieved), and before the main or standby MOSFETs start switching. This is done to minimize noise interference.

l <sub>en</sub> (Threshold)	ILIMIT				SELECT) %)
0.0-8.5 μΑ	L1	500	mA	Open	kΩ
8.5-17.7 μΑ	L2	650	mA	280.0	kΩ
17.7-33.0 μΑ	L3	750	mA	137.0	KΩ
33.0-66.0 μΑ	L4	550	mA	63.4	kΩ

Table 4. ENABLE Pin Standby Current Limit Selection.

The ENABLE pin works in a similar way to the FEEDBACK pin selection. The only difference being that the ENABLE pin is not clamped to 1 V during selection, instead remaining at 2.35 V during the detection period. Thus the selection resistor values

are slightly different for the ENABLE pin versus the FEEDBACK pin. The ENABLE pin internal current selection is chosen according to the above table.

The current limit selection for both FEEDBACK pin and ENABLE pin takes place when the BYPASS pin first reaches 4.7 V. Once the short detection period is complete, the BYPASS pin is ramped on up to 5.7 V, and the FEEDBACK pin is allowed to float to it's nominal voltage of 3.5 V.

# Standby Line Compensated Current Limit to Flatten Output Overload

For many power supplies, the power output capability of the power supply increases dramatically as the input voltage increases. This means that most power supplies are able to deliver much more power (up to 30-40% more power), into a fault overload when operating at higher input voltage (versus operating at lower input voltage). This can cause a problem since many specifications require that the output overload power capability of the device is more tightly managed.

In the case of the HiperTFS, the standby current limit is adjusted as a function of line (input voltage), in such a ways as to always provide substantially the same maximum overload power capability. The input voltage is detected via the LINE-SENSE pin current and the internal standby current limit of the device is adjusted accordingly on a cycle-by-cycle basis. This means that the HiperTFS standby will only deliver approximately 5% more overload power at high-line as it did at low-line. This feature provides a much safer design.



Figure 12. Shows Output Overload Power for Both Compensated and Uncompensated Standby Current Limits.

## Standby Line Undervoltage Detection (UV)

The LINE-SENSE pin resistor is connected to V<sub>IN</sub> and generates a current signal proportional to V<sub>IN</sub>. The LINE-SENSE pin voltage is held by the device at 2.35 V. The LINE-SENSE pin current signal is used to trigger under/overvoltage thresholds for both the standby and main converters. Assuming a LINE-SENSE pin resistor of 4 MΩ, the standby will begin operating at approximately 100 V (as defined by I<sub>L(SE\_UVON</sub>)). The standby will shutdown if regulation is lost when input voltage is below 100 V.

However the standby will be forced to shutdown if this input voltage drops below approximately 40 V (as defined by  $I_{LSB-LNOFE}$ ).

# Main and Standby Oscillator and Switching Frequency

The standby converter operates at a frequency of 132 kHz. The main converter operates at exactly half that frequency at 66 kHz. The two converters both include a common frequency jitter profile that varies the switching frequency  $\pm$ 4 kHz for the main (twice the jitter frequency range  $\pm$ 8 kHz for the standby), during a 4 ms jitter period. The frequency jitter helps reduce quasipeak and average EMI emissions.

It should be noted that the HiperTFS has a collision avoidance scheme in which the main converter is the master and the standby is the slave, which avoids the main and standby switching at exactly simultaneous moments. The most common condition would be close to 50% duty cycle, if the main (master) is about to switch (turn-off), then the standby (slave), waits for short instant (200 ns) before starting it's next cycle. The standby is used as the slave, since the ON/OFF control of the HiperTFS standby is less easily disrupted by sudden delays in switching, versus the linear control loop of the main converter.

## Standby and Main Thermal Shutdown

The HiperTFS provides a thermal shutdown function, (OTP) that protects the HiperTFS. This hysteretic thermal shutdown allows the device to automatically recover from any thermal fault event. The thermal shutdown is triggered at a die-temperature of approximately 118 °C and has a high hysteresis to ensure the average device temperature is within safe levels. In a well designed system the HiperTFS thermal shutdown is not triggered during any normal operation and is only present as a safety feature to protect against abnormal or fault conditions.

## **BYPASS (BP)** Pin Operation

The BYPASS (BP) pin is the supply pin for the entire HiperTFS device. The BYPASS pin is internally connected to a high-voltage current source via the STANDBY DRAIN power MOSFET. This high-voltage source will charge the BYPASS pin to 4.7 V during initial power up. Once the BYPASS pin reaches 4.7 V, the BYPASS pin will check the main and standby current limit selection (FEEDBACK pin and ENABLE pin resistors respectively). This selection takes a very short period, thereafter the BYPASS pin continues being charged until it reaches 5.7 V, at which point the standby power supply is ready to begin operation. Like the TinySwitch-III the high-voltage current source will continue to charge the BYPASS pin if it droops below 5.7 V. However in most typical applications, a resistor (typically 7.5 k $\Omega$ ) is connected from primary bias (12 V) to the BYPASS pin. This resistor provides the operating current to the BYPASS pin, preventing the need to draw power from the high-voltage current source. Like the TinySwitch-III, the BYPASS pin contains a shunt regulator, which will be enabled if the BYPASS pin voltage is externally driven above 5.7 V. The BYPASS pin shunt current is used for two functions:

 First, for a 4 mA threshold (I<sub>BP(ON)</sub>) for main remote-on. When the BYPASS pin current exceeds this threshold, the main is enabled.



2. Second a 15 mA threshold ( $I_{BP(SD)}$ ) for standby secondary OVP latch-off. When the BYPASS pin current exceeds this threshold, the standby and main converters are latched-off. This latch can be reset by pulling the LINE-SENSE pin below the line undervoltage threshold ( $I_{L(SB-UVOFF)}$ ), or by discharging the BYPASS pin below 4.7 V.

Note: unlike the TinySwitch-III the HiperTFS BYPASS pin capacitor does not provide any programming capability. Instead the recommended BYPASS pin capacitor should always be a 1  $\mu F$  (ceramic) capacitor.

## Main and Standby Line Overvoltage Detection (OV)

The overvoltage threshold is included in the device, and can be used to disable the device during overvoltage (with the use of an additional external signal Zener). The overvoltage threshold is set sufficiently high to prevent accidental triggering during boost PFC overshoot conditions. When the overvoltage condition is triggered, it will simultaneously shutdown both the Main and Standby. The overvoltage feature is intended for use with external components (circuitry), to program the overvoltage threshold independently of the undervoltage thresholds (see the Applications section for details).

#### High-Power eSIP Package

The HiperTFS package is designed to minimize the physical size of the device, while maintaining a low thermal impedance and sufficient electrical spacing for the pins. The package has 12 functional pins with 4 pins removed for increased pin-to-pin spacing between high-voltage pins. The low-side two-switch forward and flyback MOSFETs have a thermal impedance of less than 1 °C/W to the exposed pad on the back of the package. Since this pad is referenced to the SOURCE pin (Source), it is at electrical ground potential and thus can be connected to the heat sink without need for electrical insulation. The high-side MOSFET is over-molded to achieve electrical isolation and thus also allows direct connection to the heat sink.

#### **Output Power Table**

Product <sup>2</sup>	Two-	Two-Switched Forward 380 V				
Troduct	Continuous <sup>1</sup> (25 °C)	Continuous <sup>1</sup> (50 °C)	Peak (50 °C)	50 °C		
TFS757HG	193 W	163 W	228 W	20 W		
TFS758HG	236 W	200 W	278 W	20 W		
TFS759HG	280 W	235 W	309 W	20 W		
TFS760HG	305 W	258 W	358 W	20 W		
TFS761HG	326 W	276 W	383 W	20 W		
TFS762HG	360 W	304 W	407 W	20 W		
TFS763HG	388 W	327 W	455 W	20 W		
TFS764HG	414 W	344 W	530 W	20 W		

Table 5. Output Power Table.

Notes:

 Maximum practical continuous power in an open frame design with adequate heat sinking (assuming heat sink θ<sub>CA</sub> of <4 °C/W), measured at specified ambient temperature (see Key Applications Considerations for more information).

 Package: eSIP16/12. (Note: Direct attach to heat sink, does not require insulation SIL pad)



# **Design, Assemble and Layout Considerations**

# **Power Table**

The data sheet power table (Table 1, page 1) represents the maximum advised continuous power based on the following conditions;

- 1. Typical multi-output PC main with the following outputs +12 V, +5 V, +3.3 V, -12 V, and +5 V standby.
- 2. A boost regulated DC input for Main 300 VDC to 385 VDC minimum nominal of 375 VDC.
- 3. HiperTFS total efficiency at least 85% at full load.
- 4. Schottky high-efficiency output diodes.
- 5. DC input for Standby 130 VDC to 385 VDC.
- 6. Sufficient heat sinking and fan cooling to keep device temperature below 100 °C.
- 7. Transformer designed with nominal duty factor of 45%.

# **HiperTFS Selection**

Selecting the optimum HiperTFS depends upon the continuous output power, thermal management, (heat sinking, etc.), and maximum ambient operating temperature. OEM applications are typically 50 °C max ambient while clone PC supplies are usually specified at 25 °C ambient. Higher efficiency can be achieved with the larger devices. The maximum output power can be tailored for any given device by programming primary I<sub>LIMIT(MA)</sub>.

# Hold-Up Time

The input capacitor is a critical component in designing for a guaranteed minimum hold-up time. Proper design of the transformer's nominal duty cycle and sufficient primary winding clamp voltage for rest of Main transformer are also essential. PIXLS (PI Expert Design Spreadsheet) can compute these values or refer to formula in AN-51.

## Bias Support for High-Side Driver

Bias support for HiperTFS high-side switch is sourced from a forward phased winding of the Main transformer and should provide a minimum of 17 V at 300 VDC input (or minimum input voltage at which regulation can be maintained) to guarantee the 12 V bias required for the high-side driver is maintained.

## **Primary Bias Support**

The standby converter provides a minimum 17 V output that biases the BYPASS pin of HiperTFS. It is also the source for remote ON/OFF control and OVP. This output should be capable of delivering a minimum of 20 mA. The primary bias filter capacitor should be at 330  $\mu F$  to hold up the bias during the start-up transient.

# Start-Up

There is a duty factor soft-start function at start-up that slews from 30% duty factor to max duty factor in approximately 15 ms. The current limit during start-up is actually boosted by 115% for the first 32 ms to provide the ability to drive heavy capacitive loads and meet less than 20 ms output rise time requirement.



Figure 13. Fixed Frequency Operation Without Jitter.







Figure 15. Typical Primary Winding Clamp-to-Rail.







Figure 16. HiperTFS Layout Considerations.

#### EMI

The frequency jitter feature modulates the switching frequency over a narrow band as a means to reduce conducted EMI average and quasi-peaks associated with the harmonics of the fundamental switching frequency. This is particularly beneficial for average conduction mode where the sampling bandwidth is narrow. The modulation rate is nominally 250 Hz which is high enough to reduce EMI but low enough to have negligible effect on output ripple (rejected by control loop).

#### **Transformer Design**

It is recommended that the transformer be designed for a maximum flux density of 3000 Gauss during continuous maximum output power and a maximum peak transient flux density no greater than 4000 Gauss. The turns ratio should be chosen for a nominal duty factor of 45% at 385 VDC input to guarantee transformer reset with typical primary winding clamp-to-rail (Figure 15). For nominal duty factor of higher value it is recommend to refer to AN-51 and use PIXLS spreadsheet for optimal transformer design. Typically the transformer should have foil secondary windings for outputs above 10 amps. The primary winding should be split primary type to keep leakage inductance low.

## Standby Mode Consumption

The HiperTFS standby converter is essentially a TinySwitch-III controller which uses whole-cycle ON/OFF control. This has the benefit of operating at a low average frequency at lighter loads which increases efficiency and reducers no-load consumption.

#### **Heat Sinking**

The HiperTFS package is eSIP-16/12. There is a metal exposed pad that provides a low thermal path to the heat sink for the low-side power device and standby power device. There is also



Figure 17. HiperTFS Heat Sink Mounting.

an over-molded, electrically isolated section of the package backside that provides isolation between the heat sink and the internal high-side switch. Thermal heat sink compound, and a mounting clip providing a minimum torque of 50 Newtons, are required for good thermal performance. The heat sink temperature behind device should not exceed 95 °C to avoid activating the over-temperature shutdown of HiperTFS. Since some of the HiperTFS pins are bent towards the heat sink, there needs to be a minimum of 0.078 inches clearance between heat sink and PC board.

## **Layout Considerations**

Use a single point connection between, SOURCE pin, GROUND pin and bypass capacitor. Typically the bypass capacitor is a surface mount type and is located directly under the HiperTFS package between the GROUND pin and the BYPASS pin.

The FEEDBACK pin and ENABLE pin along with the LINE-SENSE and RESET pins should be kept away from noisy, high voltage switching areas. If it is unavoidable to have long traces connecting to FEEDBACK pins then route these traces close to quiet, low impedance traces, that act as a Faraday shield. The LINE-SENSE and RESET pins are associated with multiple series resistor sections due to the high-voltage sensing. Make sure the last resistor in series chain is SMD type and place it very close to the pin. This will minimize the pick-up of noise.

The primary auxiliary bias output rectifier and filter should be star referenced to bulk capacitor. Any Y capacitors referenced to DC primary should also be tied to quiet nodes of bulk capacitor negative or positive terminal.





Figure 18. High-Side Bias.





Figure 19. Latching Output C



Figure 20. Non-Latching Output OVP.



Figure 21. Remote ON and Standby Bias.





Figure 22. Input OVP (Latching).



Figure 23. Non-latching Input OVP.





Figure 24. Fast AC Reset of BP Latch.



Figure 25. L and R Pin Reset and Duty Limit Circuit.





Figure 26. L and R Pin Duty Limit With  $R_1 = 4 M\Omega$  and  $R_R = 4 M\Omega$ .

# **Applications Example**

# High Efficiency +12 V, 25 A Main Output and +5 V 2.5 A Standby Power Supply

The circuit in Figure 26 is an example of a design using HiperTFS providing a 300 W +12 V output forward derived Main converter and a 12 W +5 V Standby output from the flyback controller of HiperTFS. The very high integration of two full converters within a single package immediately shows the result of very low external parts count for the entire design. Both the main converter and the flyback section of HiperTFS are designed to give very high-efficiency. The main converter takes advantage of the ability to operate above 50% duty factor which lowers RMS switch currents and allows using lower voltage more efficient Schottky diodes on the output. The flyback section uses Power Integrations TinySwitch technology which is often used in designs that demand high-efficiency and low no-load input power consumption.

The design in Figure 27 is intended to work with a PFC boost front end that nominally provides a 385 VDC input. The main converter will regulate to full load between 300 VDC and 385 VDC. This voltage range guarantees greater than 20 ms hold-up time with C1 (270  $\mu$ F).

The standby section is designed to operate whether the boost PFC stage is on or off. The standby therefore is designed to operate from 100 VDC to 385 VDC which covers the normal universal input of 90 VAC to 265 VAC.

The start-up sequence is initiated with HiperTFS charging the BYPASS pin capacitor via internal high-voltage current source. Current limit selection then follows via FEEDBACK pin and ENABLE pin resistors. The HiperTFS then senses the input voltage via the LINE-SENSE pin resistor series chain R12, R13, R35. When the input voltage reaches 100 V VDC the LINE-SENSE pin UV standby threshold is reached and the standby converter turns on. After several milliseconds the standby output will reach regulation and the primary V\_{\_{\rm ON}} +12 V bias will be stable. When the input bulk voltage reaches 315 VDC which is the UV threshold for the main converter, the main converter will initiate a turn on sequence once the remote-on command from secondary is activated. The remote-on switch (SW1) on the secondary-side for this particular design allows the user to manually activate that main converter by turning on the remote-on optocoupler. In actual PC designs the remoteon would be controlled by a computer start-up command. This optocoupler sources 5 mA into the BYPASS pin of the HiperTFS which is the threshold current to start the turn on sequence for



the Main converter. The Main converter will first turn on the bottom switch to allow the high-side drive to receive the bootstrap bias. After 14 ms the Main converter will start switching both switches at 66 kHz and the main output voltage will rise. Once the regulator U5 becomes active, current will flow through the optocoupler U1. The collector of U1 will sink current out of the FEEDBACK pin to adjust for appropriate duty cycle to maintain regulation. The normal operating sink current is between 1 mA and 2 mA. There is a forward phased bias winding off the main transformer that provides sustained bias for the high-side driver. During normal and brownout operation the RESET pin senses the turn off clamp voltage via the resistor chain R6, R18, R19 and the internal controller determines the maximum safe duty factor by comparing the RESET pin current with the LINE-SENSE pin current. This features guarantees that saturation of the transformer is completely avoided in all conditions including brownout and load transients. The LINE- SENSE pin also has a UV low threshold which turns off the Main converter when the input voltage is below 215 V.

This design in particular is intended to operate with a minimum of 30 CFM airflow at full load.

Both the main and standby output have overvoltage protection from sense circuit around U4 which will source >15 mA during fault into bypass pin to cause latching shut-off of both converters. The standby uses auto-restart to protect the standby output from overpower and over-current. The main output is current limited by the selected internal primary current limit of the main switch path.



Figure 27. Schematic of High-Efficiency +12 V, 25 A Main Output and +5 V, 2.5 A Standby Power Supply.



Figure 28. Layout of High-Efficiency +12 V, 25 A Main Output and +5 V, 2.5 A Standby Power Supply.





#### Absolute Maximum Ratings<sup>(1,5)</sup>

Absolute Maximum natings.	
DRAIN Voltage High-Side MOSFET0.3 V to 530 V	Feedback (FB) Current 100 mA
DRAIN Peak Current High-Side: TFS757	Line Sense (L) Pin Voltage0.3 V to 9 V
TFS7584.5 (8.4) <sup>4</sup> A	Line Sense (L) Pin Current100 ma
TFS7595.0 (9.3) <sup>4</sup> A	Reset (R) Pin Voltage0.3 V to 9 V
TFS7605.7 (10.7) <sup>₄</sup> A	Reset (R) Pin Current 100 mA
TFS7616.1 (11.4) <sup>4</sup> A	Bypass Supply (BP) Pin Voltage0.3 V to 9 V
TFS7626.4 (12.1) <sup>4</sup> A	Bypass Supply (BP) Pin Current 100 mA
TFS763 7.2 (13.4) <sup>4</sup> A	High Side (VDDH) Supply Pin Voltage0.3 V to 13.4 V
TFS7648.3 (15.5) <sup>4</sup> A	High Side (VDDH) Supply Pin Current
DRAIN Voltage Low-Side MOSFET0.3 V to 725 V	Storage Temperature
DRAIN Peak Current Low-Side: TFS757	Operating Junction Temperature <sup>(2)</sup> 40 °C to 150 °C
TFS7584.5 (8.4) <sup>4</sup> A	Lead Temperature <sup>(3)</sup>
TFS7595.0 (9.3) <sup>4</sup> A	Notes:
TFS760 5.7 (10.7) <sup>4</sup> A	1. All voltages referenced to SOURCE, $T_{J} = 25 \text{ °C}$ .
TFS7616.1 (11.4) <sup>4</sup> A	2. Normally limited by internal circuitry.
TFS7626.4 (12.1) <sup>4</sup> A	3. 1/16 in. (1.59 mm) from case for 5 seconds.
TFS763 7.2 (13.4) <sup>4</sup> A	4. The higher peak DRAIN current is allowed while the DRAIN
TFS7648.3 (15.5) <sup>4</sup> A	voltage is simultaneously less than 400 V.
DRAIN Voltage Standby MOSFET0.3 V to 725 V	5. Maximum ratings specified may be applied one at a time,
DRAIN Peak Current Standby MOSFET 1.20 (2.25) <sup>4</sup> A	without causing permanent damage to the product.
Enable (EN) Pin Voltage0.3 V to 9 V	Exposure to Absolute Rating conditions for extended periods
Enable (EN) Pin Current 100 mA	of time may affect product reliability.
Feedback (FB) Pin Voltage0.3 V to 9 V	
Enable (EN) Pin Voltage0.3 V to 9 V	Exposure to Absolute Rating conditions for extended periods

# **Thermal Resistance**

High-Side MOSFET (θ <sub>JC</sub> ) TFS757, TFS75815 °C/W TFS759, TFS76014 °C/W	
TFS761, TFS762 13 °C/W TFS763, TFS764 12 °C/W	1. All voltages referenced to SOURCE, $T_A = 25 \text{ °C}$ .

Parameter	Symbol	<b>Conditions</b> SOURCE = 0 V; T <sub>J</sub> = 0 °C to 100 °C (Unless Otherwise Specified)		Min	Тур	Max	Units	
Control Functions								
Switching Frequency – PC Main	$f_{\rm S(MA)}$	T <sub>J</sub> = 25 °C	Average Peak-to-Peak Jitter	62	66 4	70	kHz	
Frequency Jitter Modulation Rate	f <sub>M(MA)</sub>				250		Hz	
Remote-ON Main								
BYPASS Pin Remote-ON Current	I <sub>BP(ON)</sub>	V <sub>EN</sub> = Open		3.2	3.8	4.4	mA	
BYPASS Pin Remote- OFF Current Hysteresis	I <sub>BP(OFF)</sub>				1.1		mA	
BYPASS Pin Latching Shutdown Threshold	I <sub>BP(SD)</sub>			13	15.5	17.5	mA	
Main/Standby Remote- ON Delay	t <sub>R(ON)</sub>				2.5		μs	
Main/Standby Remote- OFF Delay	t <sub>R(OFF)</sub>				2.5		μs	
Main/Standby Remote- OFF Long Time Period	t <sub>r(PERIOD)</sub>				80		μs	
Soft-Start								
High-Side Start-Up Charge Time	t <sub>D(CH)</sub>				14		ms	
Main Current Limit at Start-Up	I <sub>LIM(SS)</sub>	See N	Jote A		115		%	
Soft-Start Period						12	ms	



Parameter	Symbol	SOURCE = 0 V; T	litions [] = 0 °C to 100 °C wise Specified)	Min	Тур	Max	Units	
FEEDBACK Pin PWM Gain	DC <sub>reg(MA)</sub>	-1800 μA < I <sub>FB</sub> < -1	500 μΑ, Ι <sub>L</sub> = 60 μΑ, 60 μΑ		-70		%/mA	
PWM Gain Temperature Drift	TC <sub>DCREG</sub>				0.05		%/°C	
FEEDBACK Pin Feed- back Onset current	<sub>FB(ON)</sub>	I, = 60 μA,	l <sub>e</sub> = 170 μA		-1.1		mA	
FEEDBACK Pin Current at Zero Duty Cycle	I <sub>FB(OFF)</sub>	$T_{J} =$	I <sub>R</sub> = 170 μΑ 25 °C		-2.1		mA	
FEEDBACK Pin Internal Filter Pole	P <sub>FB</sub>				12		kHz	
FEEDBACK Pin Voltage	V <sub>FB</sub>	I <sub>FB (OFF)</sub> , I	$_{\text{FB}} = I_{\text{FB(ON)}}$		3.56		V	
LINE-SENSE Pin (Line V	/oltage)		-				1	
Line Undervoltage	L(SB-UVON)	T <sub>J</sub> = 25 °C	Threshold	21.0	25.0	29.5	-μΑ	
Threshold – Standby	I <sub>L(SB-UVOFF)</sub>		Threshold	8.7	10.5	12.7		
Line Undervoltage	I <sub>L(MA-UVON)</sub>		Threshold	76	80	84	μΑ	
Threshold – Main	I <sub>L(MA-UVOFF)</sub>	$T_J = 25 \ ^{\circ}C$	Threshold	47	53	58		
Line Overvoltage	I <sub>L(MA-OVON)</sub>	T <sub>J</sub> = 25 °C	Threshold	119	135	146	- μΑ	
Гhreshold – Main and Standby	I <sub>L(MA-OVOFF)</sub>		Threshold	135	146	164		
LINE-SENSE Pin			T 05.00	l <sub>L</sub> = 79 μA	2.25	2.4	2.55	
Voltage	V <sub>L</sub>	T <sub>J</sub> = 25 °C	$I_{L} = 149 \ \mu A$	2.45	2.6	2.75	- V	
LINE-SENSE Pin Short-Circuit	I <sub>L(SC)</sub>	V <sub>L</sub> =	= V <sub>BP</sub>		375		μΑ	
RESET Pin (Duty Limit/I	Main Only Re	emote-OFF)		1				
Reset Overvoltage	I <sub>R(MA-OVON)</sub>	T₁= 25 °C	Threshold	165	205	245	μA	
Threshold	I <sub>R(MA-OVOFF)</sub>	1 <sub>J</sub> =20 0	Threshold	175	215	255	μΑ	
RESET Pin Voltage	V <sub>R</sub>	I <sub>R</sub> = 1	55 μΑ		2.5		V	
RESET Pin Short- Circuit Current	I <sub>R(SC)</sub>	V <sub>R</sub> =	= V <sub>BP</sub>		375		μA	
		$I_{L} = 100 \ \mu A$	, Ι <sub>R</sub> = 110 μΑ		50.5			
Duty Cycle – Programmable Limit	DC <sub>LIMIT(MA)</sub>	I <sub>L</sub> = 115 μA	, Ι <sub>R</sub> = 140 μΑ		47.5		%	
C C	DC <sub>MAX(MA)</sub>	$I_{L} = 100 \ \mu A$	, Ι <sub>R</sub> = 170 μΑ		63		-	
Current Limit Programn	ning							
FEEDBACK Pin Current Limit Detection Range #1	I <sub>LIM(1)(MA)</sub>	Start-up See Note C			0-5		μΑ	
FEEDBACK Pin Current Limit Detection Range #2	I <sub>LIM(2)(MA)</sub>		rt-up Note C		5-12		μА	
FEEDBACK Pin Current Limit Detection Range #3	I <sub>LIM(3)(MA)</sub>		rt-up Note C		12-24		μΑ	



Parameter	Symbol	Cor SOURCE = 0 V; (Unless Othe	Min	Тур	Max	Units	
Maximum Current Lin	nit				1		
	I <sub>LIM(1)(MA)</sub>	TEODED	di/dt = 175 mA/µs		1.02		
	LIM(2)(MA)	TFS757	di/dt = 233 mA/µs		1.36		
	LIM(3)(MA)	– T <sub>J</sub> = 25 °C	di/dt = 291 mA/µs	1.58	1.70	1.82	
	LIM(1)(MA)	TEOZEO	di/dt = 250 mA/µs		1.45		-
	I <sub>LIM(2)(MA)</sub>	TFS758 T <sub>_1</sub> = 25 °C	di/dt = 335 mA/µs		1.95		
	LIM(3)(MA)	r <sub>J</sub> = 20 0	di/dt = 420 mA/µs	2.28	2.45	2.62	
	LIM(1)(MA)	TFS759	di/dt = 258 mA/µs		1.62		
	LIM(2)(MA)	$T_1 = 25 ^{\circ}\text{C}$	di/dt = 344 mA/µs		2.16		_
	LIM(3)(MA)	1, - 20 0	di/dt = 430 mA/µs	2.55	2.70	2.94	
	LIM(1)(MA)	TFS760	di/dt = 324 mA/µs		1.86		
	LIM(2)(MA)	$T_{1} = 25 \text{ °C}$	di/dt = 432 mA/µs		2.48		
Current Limit	LIM(3)(MA)	1, 20 0	di/dt = 540 mA/µs	2.88	3.10	3.30	A
	LIM(1)(MA)	TFS761	di/dt = 338 mA/µs		1.95		
	LIM(2)(MA)	$T_{1} = 25 \text{ °C}$	di/dt = 450 mA/µs		2.65		
	LIM(3)(MA)	r <sub>J</sub> = 20°0	di/dt = 564 mA/µs	3.07	3.30	3.53	
	LIM(1)(MA)	TFS762 - T <sub>J</sub> = 25 °C	di/dt = 360 mA/µs		2.10		- - - - -
	LIM(2)(MA)		di/dt = 480 mA/µs		2.80		
	LIM(3)(MA)		di/dt = 600 mA/µs	3.25	3.50	3.75	
	LIM(1)(MA)	TFS763	di/dt = 402 mA/µs		2.35		
	LIM(2)(MA)	$T_{1} = 25 \text{ °C}$	di/dt = 402 mA/µs		3.10		
	LIM(3)(MA)	.j _0 0	di/dt = 670 mA/µs	3.60	3.90	4.16	
	LIM(1)(MA)	TFS764	di/dt = 468 mA/µs		2.70		
	LIM(2)(MA)	$T_{1} = 25 \text{ °C}$	di/dt = 624 mA/ $\mu$ s		3.60		
	LIM(3)(MA)	J	di/dt = 780 mA/µs	4.18	4.50	4.81	
.ow-Side Main MOSF	ET				1	1	1
		TFS757	T <sub>J</sub> = 25 °C		4.87	5.60	_
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	T <sub>J</sub> = 100 °C		7.69	9.05	
		TFS758	T <sub>J</sub> = 25 °C		3.25	3.73	-
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	T <sub>J</sub> = 100 °C		4.90	5.83	-
		TFS759	T <sub>J</sub> = 25 °C		2.35	2.70	
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	T <sub>J</sub> = 100 °C		3.60	4.21	
		TFS760	$T_{J} = 25 \text{ °C}$		1.96	2.24	- Ω
DN-State	R <sub>DS(ON)</sub>	$I_{\rm D} = I_{\rm LIM(3)(MA)}$	$T_{\rm J} = 100 ^{\circ}{\rm C}$		2.80	3.29	
Resistance	DS(ON)	TFS761	$T_{\rm J} = 25 ^{\circ}{\rm C}$		1.60	1.85	-
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	$T_{\rm J} = 100 ^{\circ}{\rm C}$		2.30	2.75	-
		TFS762	$T_{\rm J} = 25 ^{\circ}{\rm C}$		1.40	1.60	-
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	$T_{J} = 100 \text{ °C}$		2.00	2.35	
		TFS763	$T_{J} = 25 \text{ °C}$		1.20	1.40	-
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	$T_{J} = 100 \text{ °C}$		1.70	2.05	-
		TFS764	$T_{J} = 25 \text{ °C}$		1.10	1.26	4
		$I_{D} = I_{\text{LIM}(3)(\text{MA})}$	T <sub>J</sub> = 100 °C		1.53	1.80	
		TFS757				150	-
		TFS758				150	-
OFF-State Drain	I <sub>DSS(D)</sub>	TFS759 V	$V_{\rm R} = 0 \text{ V}, I_{\rm BP} = 6 \text{ mA},$			150	μA
eakage Current	000(0)		= 560 V, T <sub>J</sub> = 100 °C			150	
	1	TFS761				470	



Parameter	Symbol	SOURCE = C (Unless C	Min	Тур	Max	Units	
Low-Side Main MOSFE	T (cont.)						
OFF-State Drain Leakage Current	I <sub>DSS(D)</sub>	TFS763 TFS764	V <sub>L</sub> , V <sub>R</sub> = 0 V, I <sub>BP</sub> = 6 mA, V <sub>DS</sub> = 560 V, T <sub>J</sub> = 100 °C			470 470	- μΑ
Breakdown Voltage	BV <sub>DSS(D)</sub>	$V_L, V_R$	= 0 V, I <sub>BP</sub> = 6 mA, T <sub>J</sub> = 25 °C	725			V
Rise Time	t <sub>R(D)</sub>				100		ns
Fall Time	t <sub>F(D)</sub>				50		ns
High-Side Main MOSF	1			1	1		1
0		$TFS757$ $I_{D} = I_{LIM(3)(MA)}$	$T_{J} = 25 \text{ °C}$ $T_{J} = 100 \text{ °C}$		2.12	1.76	_
		$TFS758$ $I_{D} = I_{LIM(3)(MA)}$	$T_{J} = 25 °C$ $T_{J} = 100 °C$ $T_{L} = 25 °C$		1.40	0.88	-
ON-State Resistance		TFS759 $I_D = I_{LIM(3)(MA)}$ TFS760	$T_{J} = 25 \text{ C}$ $T_{J} = 100 \text{ °C}$ $T_{L} = 25 \text{ °C}$		1.06	0.88	-
	R <sub>ds(on)(Hd)</sub>	$I_{D} = I_{LIM(3)(MA)}$ TFS761	$T_{J} = 20 \text{ °C}$ $T_{J} = 100 \text{ °C}$ $T_{L} = 25 \text{ °C}$		1.06	0.69	- Ω
		$I_{D} = I_{\text{LIM}(3)(\text{MA})}$ TFS762	$T_{J} = 20 \text{ °C}$ $T_{J} = 100 \text{ °C}$ $T_{L} = 25 \text{ °C}$		0.84	0.58	
		$I_{D} = I_{\text{LIM(3)(MA)}}$ TFS763	$T_{J} = 25 \text{ °C}$ $T_{J} = 100 \text{ °C}$ $T_{L} = 25 \text{ °C}$		0.7	0.46	
		$I_{D} = I_{LIM(3)(MA)}$ TFS764	$T_{J} = 25 \text{ °C}$ $T_{J} = 100 \text{ °C}$ $T_{L} = 25 \text{ °C}$		0.56	0.46	
		$I_{\rm D} = I_{\rm LIM(3)(MA)}$	$T_{1} = 100 \text{ °C}$		0.56	0.40	
		TFS757	J		55		
		TFS758 TFS759			82 110		-
Effective Output Capacitance	C <sub>OSS(EFF)(HD)</sub>	TFS760 TFS761	$T_{J} = 25 \text{ °C}, V_{GS} = 0 \text{ V}$ $V_{DS} = 0 \text{ V}$ to 80% $V_{DSS(HD)}$		110 140		рF 
		TFS762 TFS763			165 205		
		TFS764			205		
Breakdown Voltage	BV <sub>DSS(HD)</sub>		T <sub>J</sub> = 25 °C	530			V
		TFS757 TFS758				60 60	_
OFF-State Drain Current Leakage	I <sub>DSS(HD)</sub>	TFS759 TFS760 TFS761	V <sub>D</sub> = 424 V, T <sub>J</sub> = 100 °C			60 60 65	- μA
Carron Eoundys		TFS762 TFS763				80 110	-
		TFS764				110	
Turn-on Voltage Rise Time	t <sub>R(HD)</sub>				30		ns
Turn-off Voltage Fall Time	t <sub>F(HD)</sub>				25		ns



Parameter	Symbol	<b>Conditions</b> SOURCE = 0 V; T <sub>J</sub> = 0 °C to 100 °C (Unless Otherwise Specified)			Min	Тур	Max	Units	
High-Side Main MOSFET	Г (cont.)								
High-Side Bias Shunt Voltage	$V_{\rm DDH(SHUNT)}$	See Note B I <sub>DDH</sub> = 2 mA		11.4	12.1	12.8	V		
High-Side Undervoltage ON-Threshold	V <sub>DDH(UVON)</sub>	See Note B		10.7	11.1	11.5	V		
High-Side Undervoltage OFF-Threshold	$V_{\text{DDH(UVOFF)}}$	See Note B		9.5	9.9	10.3	V		
High-Side Shunt Hysteresis Voltage	V <sub>DDH(HYST)</sub>	See Note B		0.7	1.2	1.5	V		
Standby MOSFET						1	1	1	
ON-State		$I_{\rm DSB} = I_{\rm LIM(3)(DSB)}$		T <sub>J</sub> = 25 °C		3.7	4.37	Ω	
Resistance	$R_{DS(ON)(DS)}$			T <sub>J</sub> = 100 °C		5.5	6.25		
OFF-State Drain Leakage Current	I <sub>DSS1(DS)</sub>	$V_{BP} = 6.2 V$ $V_{EN} = 0 V$ $V_{DS} = 560 V$ $T_{J} = 100 \text{ °C}$					200	μΑ	
	I DSS2(DS)	V <sub>BP</sub> = 6.2 V V <sub>EN</sub> = 0 V		V <sub>DS</sub> = 375 V, T <sub>J</sub> = 50 °C		15			
Breakdown Voltage	$BV_{DSS(DS)}$	$V_{_{\rm BP}} = 6.2$ V, $V_{_{\rm EN}} = 0$ V, $T_{_{\rm J}} = 25~^{\rm o}{\rm C}$		725			V		
DRAIN Supply Voltage	V <sub>DSB(START)</sub>				50			V	
Standby Controller							1		
Dutput Frequency n Standard Mode	f <sub>S(SB)</sub>	T <sub>J</sub> = 25 °C	P	Average eak-to-peak Jitter	124	132 8	140	kHz	
Maximum Duty Cycle	DC <sub>MAX(DSB)</sub>	$I_{\mu} = 40 \ \mu A$		-	67	70	73	%	
ENABLE Pin Upper Furnoff Threshold Current	I <sub>DIS</sub>			-150	-115	-80	μА		
	V <sub>EN</sub>	I <sub>EN</sub> = 25 μA		2.0	2.4	2.8	- V		
ENABLE Pin Voltage		I <sub>EN</sub> = -25 μA			0.8	1.2		1.6	
BYPASS Pin Charge Current	I <sub>CH1</sub>	$V_{BP} = 0 V,$ $T_{J} = 25 \text{ °C}$			-5	-3.2	-2	- mA	
	I <sub>CH2</sub>	V <sub>BP</sub> = 4 V, T <sub>J</sub> = 25 °C			-4	-1.5	0		
BYPASS Pin Voltage	V <sub>BP</sub>	$V_{\rm DS} = 50 \text{ V}$		50 V	5.50	5.70	5.90	V	
BYPASS Pin Voltage Hysteresis	V <sub>BP(HYST)</sub>				0.80	1.0	1.20	V	
BYPASS Pin Shunt Voltage	V <sub>BP(SHUNT)</sub>	I <sub>BP</sub> = 2 mA		5.8	6.0	6.2	V		
Standby Circuit Protecti	on	·				1	·		
ENABLE Pin Current Limit Selection Range #1	I LIM(1)(DSB)		Star	t-up		0-8.5		μΑ	



	Г		T	I			
Parameter	Symbol	<b>Conditions</b> SOURCE = 0 V; T <sub>J</sub> = 0 °C to 100 °C (Unless Otherwise Specified)	Min	Тур	Max	Units	
Standby Circuit Protection	on (cont.)						
ENABLE Pin Current Limit Selection Range #2	ILIM(2)(DSB)	Start-up		8.5-18		μΑ	
ENABLE Pin Current Limit Selection Range #3	I LIM(3)(DSB)	Start-up		18-33		μΑ	
ENABLE Pin Current Limit Selection Range #4	LIM(4)(DSB)	Start-up 33-60			μΑ		
	LIM(1)(DSB)	I <sub>1</sub> = 20 μA, di/dt = 95 mA/μs, T <sub>.1</sub> = 25 °C	450	500	550	mA	
	LIM(2)(DSB)	I <sub>1</sub> = 20 μA, di/dt = 125 mA/μs, T <sub>1</sub> = 25 °C	600	650	700		
Standby Current Limit	LIM(3)(DSB)	I <sub>1</sub> = 20 μA, di/dt = 143 mA/μs, T <sub>1</sub> = 25 °C	675	750	825		
	ILIM(4)(DSB)	$I_{L} = 20 \ \mu\text{A}, \ \text{di/dt} = 105 \ \text{mA/}\mu\text{s}, \ \text{T}_{J} = 25 \ ^{\circ}\text{C}$	495	550	605		
	$\Delta I_{\text{LIM}}$	$I_{\text{LIM}} (I_{\text{L}} = 100 \ \mu\text{A}) / I_{\text{LIM}} (I_{\text{L}} = 20 \ \mu\text{A})$ di/dt = 125 mA/ $\mu$ s		80		%	
General Circuit Protectio	on		1				
Power Coefficient	l²f	$\begin{split} I^{2}f &= I_{\text{LIM}(2)(\text{DSB})(\text{TYP})} \times \ f_{\text{S}(\text{SB})(\text{OSC})(\text{TYP})} \\ T_{\text{J}} &= 25 \ ^{\circ}\text{C} \end{split}$	$0.9 \times l^2 f$	l²f	1.12 × I <sup>2</sup> f	A²Hz	
Initial Current Limit	I <sub>INIT</sub>	T <sub>J</sub> = 25 °C	0.75 × I <sub>LIM(MIN)</sub>				
Leading Edge Blanking Time (Main)	t <sub>LEB(D)</sub>	T <sub>J</sub> = 25 °C	170	215		ns	
Leading Edge Blanking Time (Standby)	t <sub>LEB(DSB)</sub>	T <sub>J</sub> = 25 °C	170	215		ns	
Current Limit Delay (Main)	t <sub>ILD(D)</sub>	T <sub>J</sub> = 25 °C		150		ns	
Current Limit Delay (Standby)	t <sub>ILD(DSB)</sub>	T <sub>J</sub> = 25 °C		150		ns	
Thermal Shutdown Temperature	$T_{SD}$			118		°C	
Thermal Shutdown Hysteresis	T <sub>SD(HYST)</sub>			55		°C	
Auto-Restart ON-Time at f <sub>osc</sub> Standby	t <sub>ar</sub>	T <sub>J</sub> = 25 °C		64		ms	
Auto-Restart Duty Cycle Standby	DC <sub>AR</sub>	T <sub>J</sub> = 25 °C		2.2		%	
Supply Current							
DRAIN Supply Current	l <sub>S1</sub>	EN Current > I <sub>DIS</sub> (No MOSFETs Switching)	400	750	1000	μA	
NOTES:	۱ <sub>S2</sub>	EN Open (Standby MOSFET Switching at f <sub>osc</sub> )			1200	(*****	

A. The current limit is boosted for the first 34 ms of main supply switching and returns to normal level after this period.

B.  $V_{\text{DDH(SHUNT)}}$  minus  $V_{\text{DDH(UV_ON)}}$  is equal to 250 mV minimum. C. Level 1  $R_{\text{FB}}$  = open, Level 2  $R_{\text{FB}}$  = 511 k $\Omega$ , Level 3  $R_{\text{FB}}$  = 232 k $\Omega$ . D. Level 1  $R_{\text{EN}}$  = open, Level 2  $R_{\text{EN}}$  = 280 k $\Omega$ , Level 3  $R_{\text{EN}}$  = 137 k $\Omega$ , Level 4  $R_{\text{EN}}$  = 63.4 k $\Omega$ .



# **Typical Performance Characteristics**



Figure 29. Main Supply. Breakdown Voltage vs. Temperature.



Figure 31. Main Supply. Frequency vs. Temperature.





Figure 30. Standby Supply. Breakdown vs. Temperature.



Figure 32. Standby Supply. Frequency vs. Temperature.











Figure 37. R Pin Voltage vs. R Pin Current.





Figure 36. L Pin Voltage vs. L Pin Current.



Figure 38. FEEDBACK Pin Current vs. FEEDBACK Pin Voltage.





# **Typical Performance Characteristics (cont.)**



Figure 41. VDDH Current vs. VDDH Voltage.



Figure 43. Duty Cycle vs. Temperature ( $I_1 = 115 \mu A$ ,  $I_8 = 140 \mu A$ )



100 PI-5949-052510 75 Duty Cycle (%) 50 25 0 -25 25 50 75 100 125 -50 0 Temperature (°C)

Figure 42. Duty Cycle vs. Temperature ( $T_J$  = 100 µA,  $J_R$  = 110 µA).



Figure 44. Standby Supply. Output Characteristics.







Figure 47. Main Supply. Drain Capacitance vs. Drain Voltage.



Figure 49. Main Supply. Power vs. Drain Voltage.



Figure 51. High-Side MOSFET Drain Current vs. Drain Voltage.



Figure 48. Standby Supply. Power vs. Drain Voltage.



Figure 50. High-Side MOSFET Drain Current vs. Drain Voltage.





# **Typical Performance Characteristics (cont.)**



Figure 53. High-Side MOSFET Power vs. Drain Voltage.





#### Part Ordering Information

Option	Quantity
Tube	30
	Tube Tube Tube Tube Tube Tube Tube Tube

#### Part Marking Information





Revision	Notes	Date
В	Initial Release.	11/09/10
С	Updated Absolute Maximum Ratings section. Updated TFS759 ILINIT, Figures 3, 25, 41, and Package drawing.	02/11
D	Corrected Tables 3 and 4. Added Line Undervoltage Threshold-Standby limits. Updated LINE-SENSE Pin Voltage. Corrected page 35.	05/12
Е	Moved location of "output over current protection (OCP)" bullet point and "output short-circuit protection (SCP)" bullet point on page 3.	04/15

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