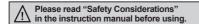
Manual Handle Type Incremental Rotary Encoder

Features

- Suitable for manual pulse input type such as numerically controlled or milling machinery
- Terminal connection type
- Power supply: 5VDC ±5%, 12-24VDC ±5%

Applications

Industrial tooling machinery



CE



CONTROLLERS

MOTION DEVICES

SENSORS

SOFTWARE

Ordering Information

ENH	- 100 -	- 1	- T -	24
Series	Pulses/revolution	Clickstopper position	Control output	Power supply
Handle type	125 100	1: Normal "H"	IV: Voltage output	5: 5VDC ±5% 24: 12-24VDC ±5%

Specifications

XThe power of Line driver is only for 5VDC.

Item			Manual Handle Type Incremental Rotary Encoder	
Resolution (PPR) ^{×1}		PPR) ^{※1}	25.100	
11030	Output phase		A, B phase (line driver output A, Ā, B, B̄ phase)	
۔	Phase difference of output		Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T= 1 cycle of A phase)	
	Control output	Totem pole output	[Low] - Load current: max. 30mA, Residual voltage: max. 0.4VDC= [High] - Load current: max. 10mA Output voltage (power voltage 5VDC=): min. (power voltage-2.0)VDC=, Output voltage (power voltage 12-24VDC=): min. (power voltage-3.0) VDC=	
atio		Voltage output	Load current: max. 10mA, Residual voltage: max. 0.4VDC	
Electrical specification		Line driver output	• [Low] - Load current: max. 20mA, Residual voltage: max. 0.5VDC== • [High] - Load current: max20mA, Output voltage: min. 2.5VDC==	
	Respon	se Totem pole output	-Max. 1μs (cable length: 1m, I sink = 20mA)	
	time (rise/fall)	Voltage output		
		Line driver output	Max. 0.2µs (cable length: 1m, I sink = 20mA)	
	Power supply		• 5VDC== ±5% (ripple P-P: max.5%) • 12-24VDC== ±5% (ripple P-P: max.5%)	
	Current consumption		Max. 40mA (disconnection of the load), Line driver output: max. 50mA (disconnection of the load)	
	Max. response frequency		10kHz	
	Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)	
	Dielectric strength		750VAC 50/60Hz for 1 minute (between all terminals and case)	
	Connection		Terminal block type	
	Starting torque		Max. 1kgf·cm (0.098N·m)	
		Shaft loading	Radial: max. 2kgf, Thrust: max. 1kgf	
spec	ification	Max. allowable revolution ^{*2}	Max. 200rpm (normal), 600rpm (peak)	
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours	
Shock			Approx. max. 50G	
Environment Ambient temperature Ambient humidity		Ambient temperature	-10 to 70°C, storage: -25 to 85°C	
		Ambient humidity	35 to 85%RH, storage: 35 to 90℃	
Protection structure		ucture	IP50 (IEC standard)	
Approval			C € (except for line driver output)	
Weight ^{**3}			Approx. 330g (approx. 260g)	

X1: Not indicated resolutions are customizable.

[Max. response revolution (rpm)= | Max. response frequency | Resolution | × 60 sec]

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

Vision Sensors (F) Proximity Sensors

> G) ressure

H) Rotary

Connectors/ Connector Cables. Sensor Distributio Boxes/ Sockets

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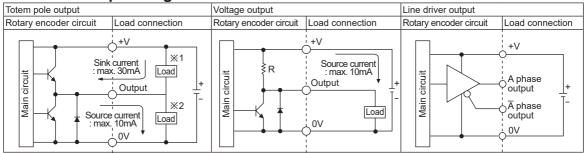
X2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

X3: The weight includes packaging. The weight in parenthesis is for unit only.

^{*}Environment resistance is rated at no freezing or condensation.

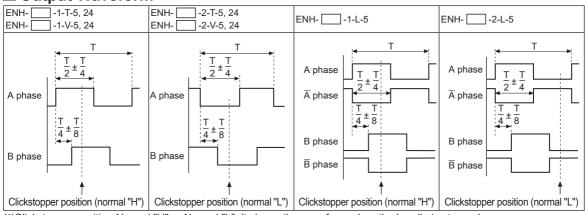
ENH Series

Control Output Diagram



- The output circuits for A, B phase (line driver output is A, A, B, B phase) are same.
- Totem pole output can be used for NPN open collector type (%1) or voltage output type (%2).

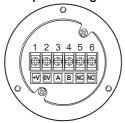
Output Waveform



XClickstopper position Normal "H" or Normal "L": It shows the waveform when the handle is stopped.

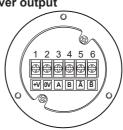
Connections

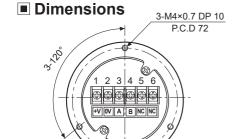
•Totem pole output / Voltage output



XDo not use terminal No. 5, 6.

Line driver output





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Autonics State of the state of

(unit: mm)

XØ70mm P.C.D mounting hole type is customizable.

XFix the unit or a coupling by a wrench under 0.15N m of torque.

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